

Hauptseminar

Modelling of the Tamagotchi with AUTOFOCUS

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Abstract

We have modelled the Tamagotchi with AUTOFOCUS.

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1 Introduction

1.1 Circumstances

We are one of eight groups modelling the Tamagotchi — each with another CASE¹ tool.

Except some basic knowledge about concepts of Software Engineering we did not know anything about our issue. We knew that there must be something and people call it CASE and mean Computer Supported Software Engineering but we had never seen a CASE tool and — of course — we did not know how many windows you have to deal with when you work with a CASE tool.

1.2 Purpose of the Notation/Method

”The purpose of AUTOFOCUS is to aid software developers in specifying and designing distributed systems, especially so-called ‘embedded systems’.”
(out of Autofocus Users Manual)

1.3 History of Development, Authors

”AutoFocus was developed and implemented during the one-semester practical course ‘Software Engineering’ by students and members of the chairs Prof. Broy and Prof. Endres at the faculty of computer science at the Technische Universität München in summer 1996. It will be used and enhanced in several cooperation projects with Bavarian industrial companies, including Siemens Public Networks.”
(out of <http://autofocus.informatik.tu-muenchen.de/Infos/afinfo-en.html>)

1.4 A Survey of the Notation/Method

1.4.1 Conceptual Model of the Notation/Method

With AUTOFOCUS you can model four different views on your system, accessible from a modelling center (figure 1): SSDs, STDs, EETs and DTDs (see table 1 and figures 3, 4, 5).

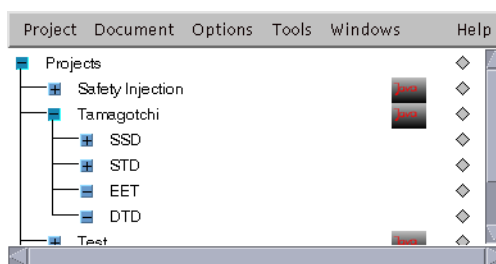


Figure 1: Modelling Center

¹CASE: Computer Supported Software Engineering

SSD	(System Structure Diagrams) to specify the static communication structure of a distributed system as a network of interconnected components. An SSD can either have a sub-SSD or an STD (see below). With the sub-structure you can build up your system in a hierarchical way to not lose your grip on it. All the system's components described by the SSDs work in parallel. An component can have a set of properties (figure 2) that can only be accessed by its own STD, not even by the component STDs of its sub-SSDs.
STD	(State Transition Diagrams, or automata for short) to model the behaviour of a system's components (i.e., the state transitions dependent on the data a component reads). Again, you can use hierarchical technique on it: every state can be splitted up in a sub-STD. Technically this sub-STD is on the same level as its parent and has access to the same properties.
EET	(Extended Event Traces, see Message Sequence Charts) to describe the behaviour of a (part of a) system from a view based on the communications history between several components. EETs can be automatically created while simulation of a component.
DTD	(Data Type Definitions) to describe data types, and some functions working on them. DTDs are a textual description technique.

Table 1: Views in AUTOFOCUS

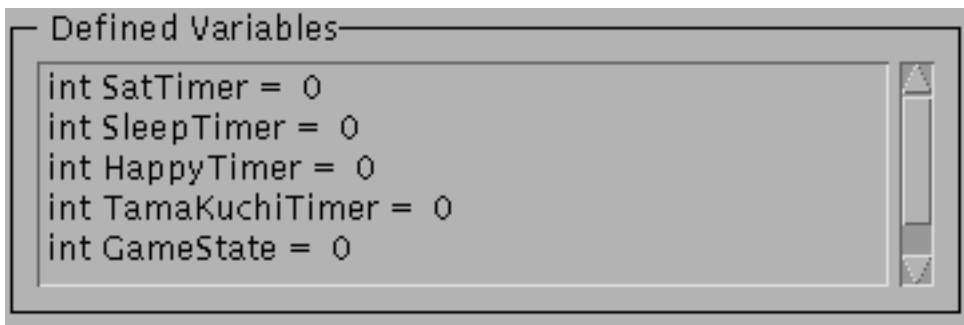


Figure 2: Properties of a component

1.4.2 Methodology, HOWTO use AUTOFOCUS

You are not forced to follow any given sequence, but in the current version of AUTOFOCUS it is impossible to connect a sub-structure to its parent without designing the parent first. But you can very well assign an STD to its SSD in any situation.

Anyway, a recommendable order of constructing views is to design the top level SSDs first, think about their responsibilities and connect them with channels according to the information to be exchanged.

If you already have use cases, you can describe their information flow with EETs and avoid forgetting important functionality. As soon as your components get their behaviour, AUTOFOCUS can check if the described system can perform your use cases.

Then you should try to divide the responsibilities of each component into sub-SSDs as long as you find possibilities to make them work in parallel. Be aware that in the current version of AUTOFOCUS you can only simulate components with sub-SSDs but not with an STD assigned to the component itself. However, you can set a pseudo component between the component to be simulated and its STD. It means stupid work, but then you can simulate and debug your SSD.

The behaviour of every component which has no sub-SSD is to be designed now with

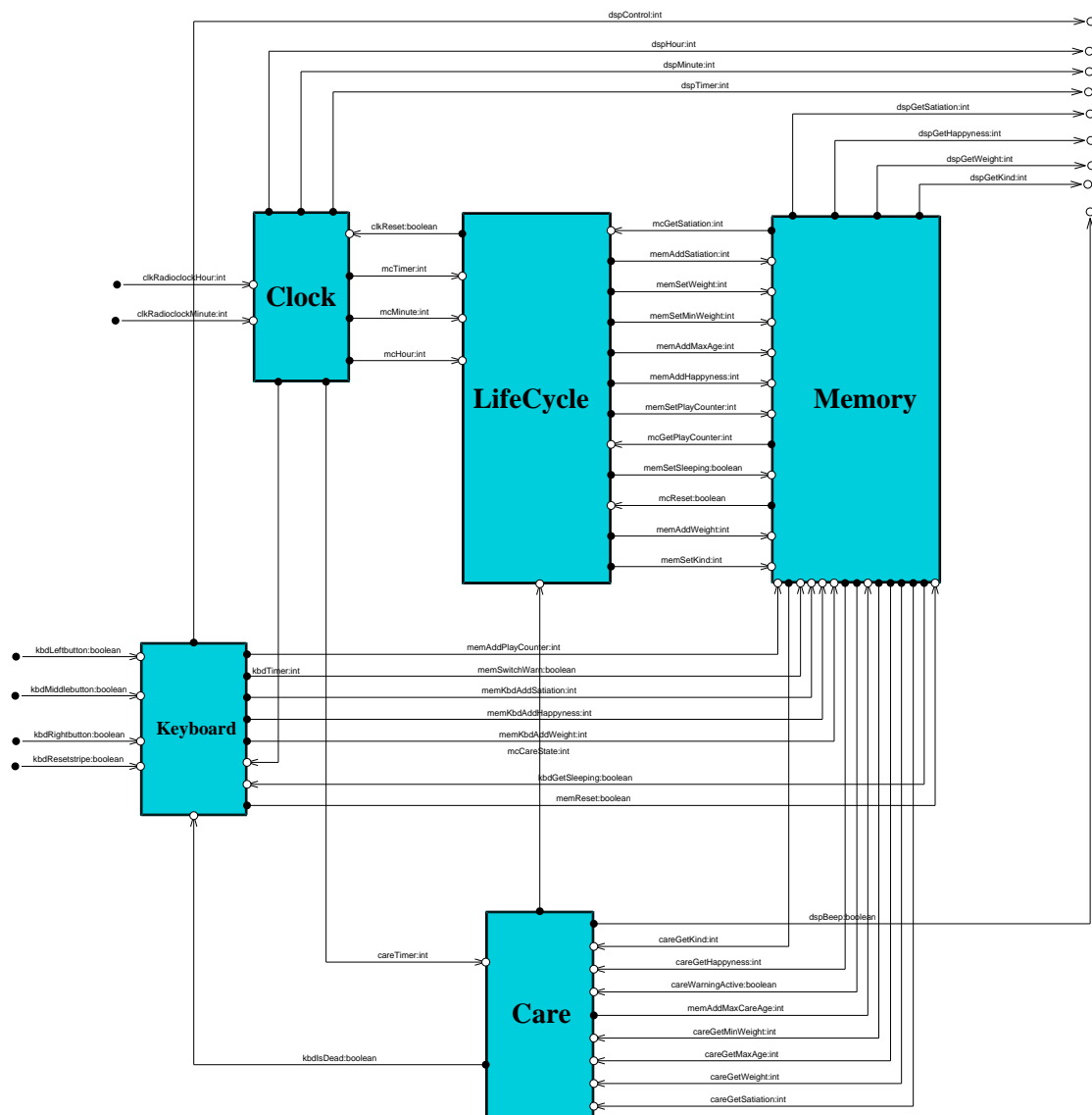


Figure 3: System Structure Diagram

an STD. Make sure that this STD is easy to understand. Collect similar states in a single state and describe them in its sub-STD. It helps to oversee your STDs.

When you are ready with modelling a component with all its sub-components and their functionality, you can simulate it. Try to simulate as soon as possible to make sure that you cover as many use cases as possible. This is another reason to make the components become easy.

1.4.3 Modelling

There are no guidelines in the manuals respectively texts of AUTOFOCUS describing, how things of the real world should be represented in the notation's concepts (e.g. how to represent states). But in consequence of the simplicity that is given by only four different kinds of views it should be possible to understand the idea behind the notification without a tutorial. However, a complete list of the tool's special operating needs could help a lot.

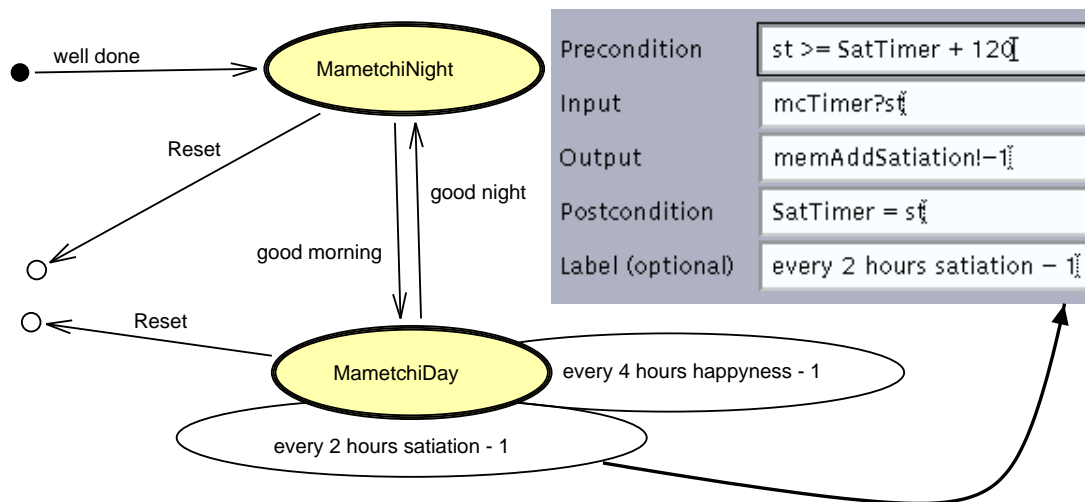


Figure 4: State Transition Diagram

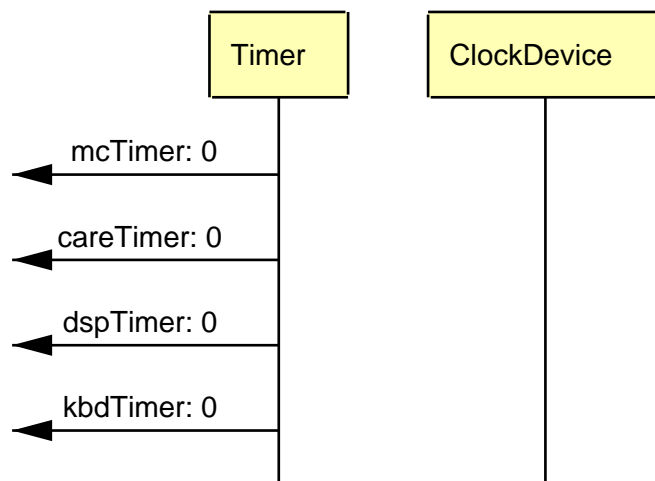


Figure 5: Extended Event Trace

1.5 A Survey of AUTOFOCUS

1.5.1 Basic features of AUTOFOCUS ...

Simulation. As long as you only use standard java data types and java based state transitions you can simulate your system in a mighty simulation environment. Interactivity is provided by the user being able to send data into the input channels of the simulated component. Both the state transitions and the activities and values of the channels can be watched in their according diagrams during simulation and in real time. An EET that represents the communication history of the simulation can be created automatically. It shows all the direct sub-components of the simulated component and, of course, the communication between them.

Consistency-Check. We have not used it and therefor we do not have any experience with it. (...)

Interface to the Tool's Environment. Just as Consistency-Check we did not use it, but there had been a project before in which AUTOFOCUS had been commanding a real existing 'Fischertechnik' model of an elevator system.

Platform Independence. AUTOFOCUS is completely written in Java, i.e., you can use it on any platform you can find Java for. However, the AUTOFOCUS server needs a UNIX environment.

Multi User Capability. AUTOFOCUS is designed to be a client server architecture. An arbitrary (is it really arbitrary?) number of developers can work on a project at the same time. Each view of the project that one works on is locked for the others. The server should always be started within the same UNIX account due to access rights of the data storage files. Unfortunately it is not recommendable to develop parts of the project without connection to the server, because diagrams cannot be transferred between different projects well enough. Maybe this restrictions will disappear when the data storage of AUTOFOCUS will be reengineered using a database management system, which is planned.

2 Approach and Result

2.1 Which Concrete Strategy has been Followed with Regard to Modelling?

First of all we discussed the top level components and their basic communication channels drawing everything on a sheet of paper and made a hardcopy of it for all of us.

Then the LifeCycle and the Clock were designed in parallel. That was possible due to the little amount of communication between them.

After development of the LifeCycle had been proceeded far enough to exactly know which functionality the Memory should provide we started to design this and also the Care component which is very closely connected to the Memory. Due to that Memory and Care were created by the same developer.

The Keyboard component was designed time-independently but with very active coordination to the development of Memory.

2.2 How have the Requirements been Devided and how have the Interfaces been Defined?

All of us were responsible for one or two components each (see table 2).

Alexander Seitz	LifeCycle and AUTOFOCUS learning
Thomas Seliger	Clock and Keyboard
Florian Kunkel	Memory and Care

Table 2: Divide and Conquere

AUTOFOCUS supported us by providing multi user capability. We had to work in the same room at the same time but were able to work on our components in parallel.

2.3 Scope/Precision of the Specification

Did we model all of the requirements exactly? No, we did not. There is no display. The Memory does not check its values (e.g., satiation can be greater than 4). Our Tamagotchi cannot starve. If the Tamagotchi's properties are not in their green ranges, there is a signal every minute. Not every state transition is deterministic. The timer (Clock) is not more detailed than one minute.

2.4 Did we Already Simulate while Modelling?

Yes, we did. Every component has been simulated separately. AUTOFOCUS did a very good job according to this.

2.5 Verification/Validation of the Specification

2.5.1 Is the Specification Consistent and Complete?

Not completely (see above).

2.5.2 Has the Specification been Reviewed Completely According to the Requirements?

Due to the inconsistencies of the requirements itself, it was not really easy to make sure that every requirement is satisfied. But we tried to fulfil them all.

2.5.3 Has the Specification been Tested Completely, Supported by the Tool and According to the Requirements?

Testing all the requirements manually was nearly impossible, because we could not save the state of our Tamagotchi's life. If we wanted to do so, we would have had to play the game again and again. The only thing we did was playing several times to make sure that it works at all.

2.5.4 Statement about Problems with Consistency Check, Review or Simulation

We had not the time to work with the consistency check, but AUTOFOCUS supports review and simulation quite well.

2.5.5 Has the Specification been debugged?

In consequence of simulating every single component with sub-components we debugged during development and of course we did fix it whenever we found a bug. Exceptions are found above.

2.6 Size of the Specification

We designed 6 SSDs and 33 STDs.

3 Specification of the Funktionalität "Playing"

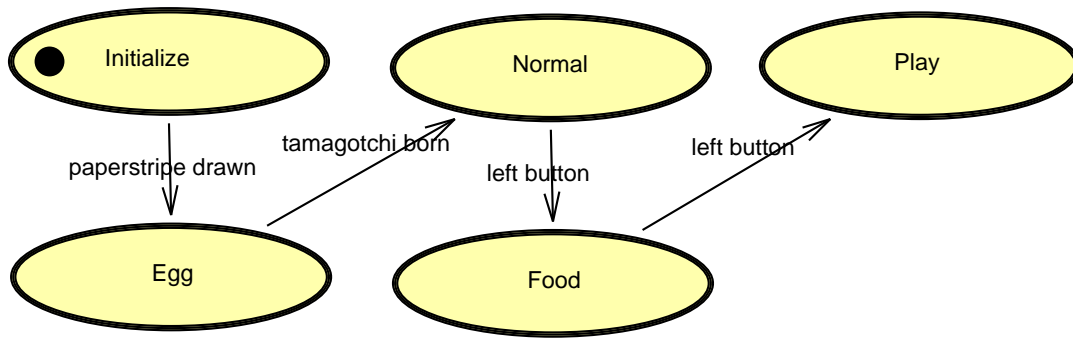


Figure 6: simplified menu-logic

The State-Transition-Diagram figure STD 6 shows the simplified menu logic. The full STD can be found in the appendix. The automaton starts at the initial-state "Initialize" and waits until the paperstripe will be drawn. If this is done, the automaton has to stay five minutes in the "Egg" - state before the state "Normal" is achieved.

To get to the state named "Play", the user must press the left button twice. This activates the two transitions labeled "left button". The state "Play" contains a sub-automation, which handles the complete game.

This sub-automaton shows figure STD 7. It continues at the state "PlayMain" which is the target of the second transition labeled "left button" transition coming from the superior "Play" state. The actual game starts, if the user presses the middle button.

The responsible transition attributes looks like this:

PlayMain \implies NewRound	
start game	
Input	reset?, kbdMiddlebutton?true, kbdTimer?x
Output	dspControl!41
Postcondition	Round=0; RoundsWon=0; Savetimer=x

Start game will be activated, if no reset signal is present and the middle button is pressed (signal from "kbdMiddlebutton"). The actual time value x is stored in the "Savetimer" variable and will be used as timeout-timer ("kbdTimer" is always valid). x is called a transitions-local-variable and is only present in this transition. It's used as a temporary memory to read the signal from the port "kbdTimer" and store it in the SSD-local-variable "Savetimer". To show a playing tamagotchi on the the display, the constant 41 is sent over "dspControl". At last the variables "Round" and "RoundsWon" are set to zero.

To leave the game, the user has to press the R-key ("about game"). It will also be left if the timeout occurs ("time passed"), the tamagotchi starts sleeping ("starts sleeping") or the user pushes the paperstripe ("reset").

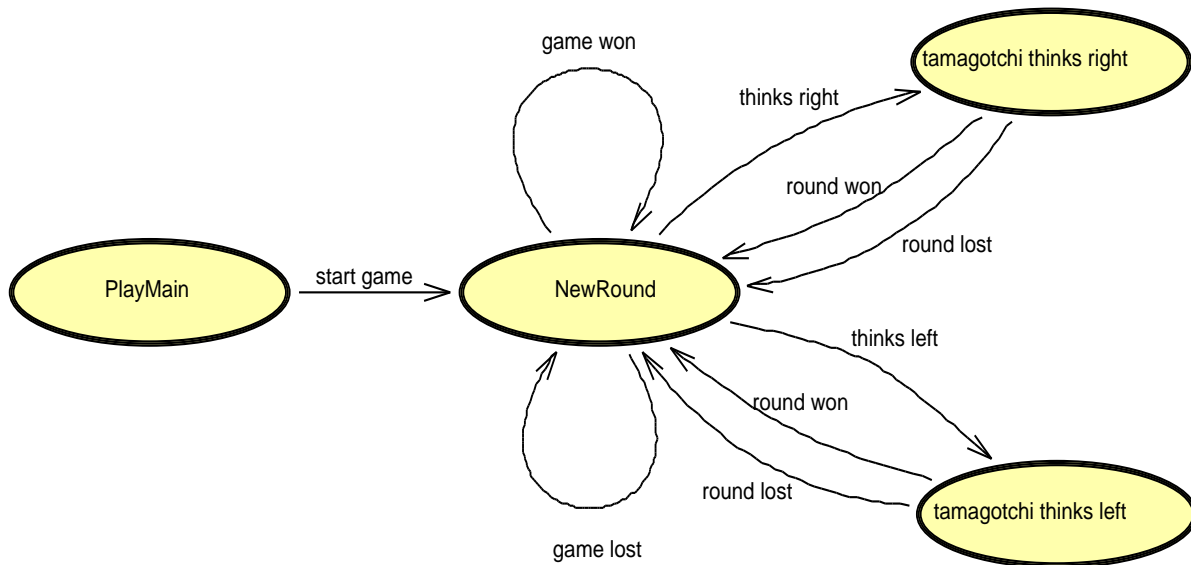


Figure 7: simplified game

NewRound \Rightarrow tamagotchi thinks left thinks left	
Precondition	Round<5
Input	reset?, kbdGetSleeping?false
Output	dspControl!41

NewRound \Rightarrow tamagotchi thinks right thinks right	
Precondition	Round<5
Input	reset?, kbdGetSleeping?false
Output	dspControl!41

Now we are at “NewRound” and the tamagotchi is looking left and right (the display component is also responsible for beeping). At first the tamagotchi selects a direction. This is done by the two transitions “thinks left” and “thinks right”. Both transitions have the same pre- and input-condition. Because of this situation is not deterministical AUTOFOCUS randomizely selects on of the two transitions. The the display receives again 41 because the use may not yet see, what the tamagotch is thinking and the automaton changes into the “tamagotchi thinks right” or “tamagotchi thinks left” state. Now its the users turn to guess the direction the tamagotchi is thinking of.

tamagotchi thinks left \Rightarrow NewRound round won	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!44
Postcondition	Round++; RoundsWon++

Supposing the tamagotchi thinks left, then we are in the state “tamagotchi thinks left”. If the user selects the middle button (signal from “kbdMiddlebutton”), then the transition “round won” will be activated because the users choice is wrong and the tamagotchi has won this round. The display receives the constant 44, which stands for a playing tamagotchi looking left happily. The variables “Rounds” and “RoundsWon” in the post-condition are both increased by one.

tamagotchi thinks left \implies NewRound	
round lost	
Input	reset?, kbdLeftbutton?true
Output	dspControl!45
Postcondition	Round++

When the left button is pressed by the user, he has guest tamagotchis choice and the round is lost from tamagotchis point of view. Therefore the transition “round lost” is activated. The display receives now the value 44, which stands for a playing tamagotchi looking left sadly. “Rounds” is increased by one and “RoundWon” stays equal. Again we are at the “NewRound” state and round two starts.

NewRound \implies NewRound	
game won	
Precondition	Round==5 && RoundsWon>2
Input	reset?, kbdTimer?x, kbdGetSleeping?false
Output	dspControl!41, memKbdAddHappyness!1, memKbdAdd-Weight!-1, memAddPlayCounter!1
Postcondition	Savetimer=x; Round=0; RoundsWon=0

NewRound \implies NewRound	
game lost	
Precondition	Round==5 && RoundsWon<3
Input	reset?, kbdTimer?x, kbdGetSleeping?false
Output	dspControl!41, memKbdAddWeight!-1, memAddPlayCounter!1
Postcondition	Savetimer=x; Round=0; RoundsWon=0;

The procedure described above is repeated for rounds two to five. If five rounds are over (the variable “Round” has reached the value 5), the game is over and the transition “game won” or “game lost” is activated. The game is won if at least three rounds of five are won (the games the tamagotchi has won are stored in “RoundsWon”). In this case the happyness is increased by one and the weight is decreased by one. This is done by sending 1 to “memKbdAddHappyness” and -1 to “memKbdAddWeight” which adds and subtracts the givel value. Instead of a Get- and Set-function-pair for each memory-port, this method has the advantage that more than one module can alter the values at the same time whitout interfering with each other.

The signal “memAddPlayCounter” is used for the lifecycle component and has no effect on the game. “kbdGetSleeping” cares, that a new game can only be started, if the tamagotchi is awake. This signal is, like “kbdTimer” and the memory-signals always present. At least the variables “Rounds”, “RoundsWon” and “Savetimer” are again initialized for the next game and the display is directed to show a tamagotchi looking left and right (value 41 to port “dspControl”).

3.1 Realisation of the informal demands

Overview and SSDs To get a structure overview the tamagotchis components are modelled through System-Structure-Diagrams (SSD) and Sub-System-Structure-Diagrams (Sub-SSD). Each component has its own functionality, which implementation is hidden in this view. Behind some Sub-SSDs like the “Memory” are separate Sub-SSDs which give again an overview of this special component (the “Memory” is divided in memory-cell Sub-SSDs).

The components are connected to each other, so it can be seen which component sends signals to another component. For example, the “LifeCycle” has to alter many variables in the memory. Because the signals are one-way, two ports are necessary, one for reading and one for altering a variable.

Functionality and STDs If no refinement is necessary, the proper functionality of the (Sub)components is specified in State-Transition-Diagrams (STD) and their Sub-STDs. The memory-cells in “Memory” are all single automata, which handle the Get- and Add-operations.

The individual states of the tamagotchi are represented in the states of the State-Transition-Diagrams. A good example is the “LifeCycle” diagram. For each life-period exists an own state. Some of this states consists of an own easy to read Sub-State-Transition-Diagram. If the tamagotchi is a “Mametchi” and is sleeping, the state “MametchiNight” is active.

Timer Another important functionality is the timer. In other CASE-tools, there is an explicit timer provided by the CASE-tool. In AUTOFOCUS there is no such timer, which can easily be used. The timer in our tamagotchi is implemented in the “Clock”-component. In this component there is a clock, to count minutes and hours, and a timer, which counts only minutes. The timer is implemented with a SSD-local variable, which is increased in every step by one minute. The timer-signal is sent in every step, so a component can read a valid timer-value at any time needed.

The same technique is used by the “Memory”. Its easier to send the actual memory-cell-content at every step instead of doing complex synchronisation, because the other components can use the memory at every time they want.

4 Experiences

4.1 Training Period

The first project we have done with AUTOFOCUS was the Safety-Injection-System. This simple project took approximately 16 hours work in, design and completion. There are some difficulties in learning AUTOFOCUS. With AUTOFOCUS comes only a short and simple documentation which describes only the concepts and the menu-structure of the program. For example, is it described that there are some transition-attributes and how they are named. But what you have to fill in and which possibilities there are is missing. You have no chance to guess yourself how it works if there is nobody who can help you. But god thanks we had someone (thanks to Bernie) who could explain us the hidden features of AUTOFOCUS.

If we had overcome this hurdle the work in was fast and easy. But the user interface handling is too complicated and not intuitive. For example, the attributes-dialog, which is used very often, is only reachable in the menu and has no key-shortcut. And the window

positions are not saved. This is especially annoying in the simulator, where many windows must be opened every time.

When we worked with AUTOFOCUS there were 3 new versions coming out. On the one side, it's very good, because more functions were implemented or worked more correct, but there is no history list, where the changes are noticed. Therefore we had to test every new update. The greatest advantage was, that we could simulate each component alone. One big problem we had, that if we worked at home with the linux port from AUTOFOCUS and wanted to merge our work together to one project, was not possible, because the cut/copy/paste and the import/export functions did not work correctly.

At the beginning we didn't realize the cycle-concept correctly. If you want to catch all possibilities you have to take every port at every cycle in a STD into consideration. Even the possibility that no signal is present at one port. The more ports there are, the more complex are the transition-conditions. We minimized the problem thereby we defined some signals, that are present at every cycle (like the timer and memory signals).

4.2 Tamagotchi implementation duration

The complete development took about 140 hours. This time can be divided into four parts.

First we made a rough structure of the tamagotchis components and how they have to interact with each other. Then we defined the components interface, which channels have to be used and the name and type of the ports. Half of this work was not done with AUTOFOCUS, but on paper. Approximately 15% of the time were required for this task.

The components modelling and implementation has been done in approximately 25% of the time. This means drawing the System-Structure-Diagrams, the State-Transition-Diagrams and the transition attributes.

Testing and debugging with the help from the simulator has been taken approximately 10%. Correction of our own errors included.

The remaining 50% has been spent to the problems with AUTOFOCUS. This time is divided up to the points mentioned above. It's not easily possible to assign the problems to one phase of our work. Our problems with AUTOFOCUS were conditioned by some bugs, the complicated user interface, incomplete documentation and only partial implementations of functions, which we noticed unfortunately later at work that they are not complete. Sometimes the clients and sometimes the server stopped working and we had to restart AUTOFOCUS. Not only once it has happened, that the last work we have done was lost and we had to do it once again. Another time, AUTOFOCUS disconnects the memory-Sub-SSD, which is very complex, from its higher SSD and there is no way in AUTOFOCUS to reconnect an existing Sub-SSD. Because this component took a long time to create, we searched for another way to repair it. We analyzed the files in the repository and altered manually the internal database structure.

4.3 Modelling the Tamagotchi

Notation The representation of the System-Structure-Diagrams and State-Transition-Diagrams is very clear and easy to understand. The diagrams are not overloaded and there are no mystical signs. Everyone who is familiar with automata can understand the graphics and how it works. The clearness is among other things achieved with the help of sub-diagrams. Every component in a SSD can have an own SSD inside. So you can only see what is necessary and the details are hidden. The same technique is used for states in STDs.

A disadvantage is, that the more sub-diagrams you have, the more windows you have to open, if you want to edit something or simulate your model. If you don't assign transition

labels, all attributes are displayed in one row. It would be better to have a well-formatted, multiline string, so you can easily see the conditions of the transition, and which variables are affected.

Another disadvantage in SSDs is the amount of channels between the components. For every signal in every direction an own channel is necessary. If there were bidirectional channels or a bus-system, many things could be done easier and the clearness of the representation would raise.

Starting Problems We had some problems to understand the mechanism behind transition-local-variables, SSD-variables, ports and their combination. Here is an example:

KuchitamatchiKuchitamatchiNight \implies KuchipatchiKuchipatchiNight not good	
Precondition	T > NextStateTimer+7200 && C <= 2
Input	mcTimer?T, mcCareState?C
Output	dspMCState!14, memWeight!20, memMinWeight!20, memAdd- MaxAge!12
Postcondition	SatTimer = T; HappyTimer = T

In this transition there are two transition-local-variables (“T” and “C”). First the Input-line is executed. If the Input-line is true, a signal from the port “mcTimer” and a Signal from “mcCareState” must be present. The values are stored in the transition-local-variables “T” and “C” and the Precondition-line is evaluated. There the values of “T” must be greater than “NextStateTimer+7200” and “C” must be less or equal than 2. If all these conditions are met the transition is activated and the signals in the Output-line are sent. At last, the value of the transition-local-variable “T” is stored in the SSD-variable “SatTimer” and “HappyTimer”.

Secondly, the visiblensness of the SSD-variables is not obvious. These variables are only visible in one SSD and not in its Sub-SSD.

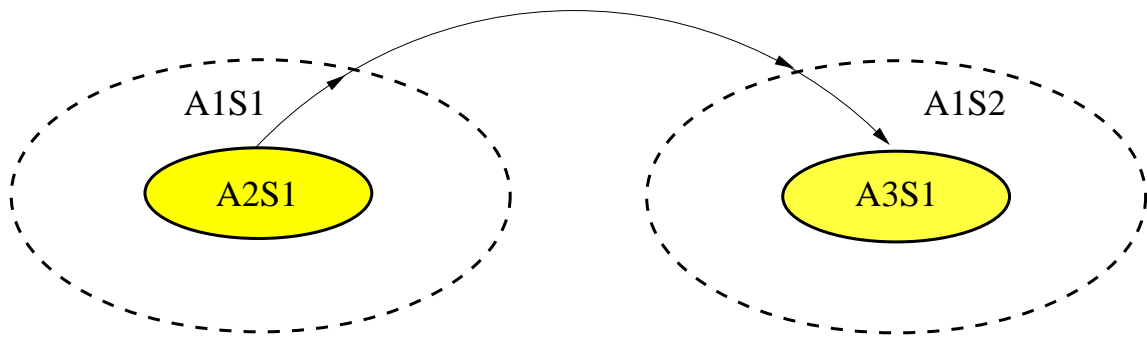
These problems we had would be no problems, if they were declared in the manual.

Tool A very positiv feature of the actual version from AUTOFOCUS is the possibility of simulating individual components. This is helpfull for complex systems, where many components are put together to one big system. A restriction in AUTOFOCUS is, that a component (SSD) can only be simulated separately, if this component has sub-components. Again one thing, that is not mentioned in the manual and that we found out by chance.

Another feature are Consistency-Checks. There are checks for guaranteeing that all channels are connected, there are no empty ports, etc. Own checks can also be defined. We didn’t use Consistency-Checks, because they didn’t work correctly in all the version of AUTOFOCUS we used.

Later changes in the strucure of the modell are complicated. One example: If you have two states (A1S1, A1S2) in an automaton A1 and these state have both a sub-automaton (A2, A3). A state (A2S1) in sub-automaton A2 is connected with a state (A3S2) in sub-automaton A3, then you have three transitions with the same transition-attributes, although it is logically the same transition:

1. from state A1S1 to A1S2
2. from state A2S1 to A1S1
3. from state A1S2 to A3S1



If you want to change e.g. the Input-condition, you have to alter all three Input-conditions. All three attributes must exactly be the same, because AUTOFOCUS recognises these three transitions as one transition through the textual attributes entered in the corresponding dialog-box. But, it is planned, to give AUTOFOCUS an object-oriented structure, so this problem won't be existant in the future any more.

Some more problems caused the non-existent error-check. In the dialog-boxes you can type in what you want and AUTOFOCUS accepts it. To check, if your input is correct, you have to simulate the component. And if you don't work on a fast machine, the preparations for the simulation (create java-classes, compile code and execute it) is too long. Especially if you are a beginner in AUTOFOCUS and e.g. are unsteady in the syntax of the transition-attributes, which is not described in the manual, it would be a great help, if the input would be check for correctness.

Errors are hard to find, because to find them, the component has to be simulated. The simulator first generates java-classes from the SSDs and STDs and then compiles the generated code. If something is wrong (e.g. channel-names, transition-attributes), you get many error-messages from the java-compiler. From this messages, you have to conclude where the real errors are. Sometimes, it's necessary to look into the generated java-code, to locate the error and find the cause.

5 Conclusions

5.1 Teamwork with autofocus

AUTOFOCUS comes with a good teamwork support. After we got used to some peculiarities of AUTOFOCUS the teamwork features were saving a good amount of time. AUTOFOCUS Server architecture is client/server based, so we could start one server and different people could work on different parts of the specification at the same time using multiple AUTOFOCUS clients.

To get the most out of distributed teamwork we had divided the specification into a few subcomponents. These subcomponents were connected to each other by channels, so we could start to work distributed after specifying the general interface (the names and types of the interconnecting channels).

If a client accesses a part of the specification (e.g. a certain system structure diagram), this part is locked and no other client may alter this part. Locking of a document is shown in the project browser. Also a locked document can be viewed in read only mode by other clients, while it is edited. After the user of the client closes the edit window, the document gets editable by other clients again.

The latest version of AUTOFOCUS we used also supported simulation of subcomponents correctly. This is a very useful feature, as we could test small subcomponents for bugs. This reduced the possible errors and made it possible to simulate parts of the tamagotchi, although essential parts of the tamagotchi were not realized in AUTOFOCUS at this time.

Although the teamwork support of AUTOFOCUS is already very good, there are some peculiarities that costed time: The server should be always started by the same person, as the server runs with the user identity of the user that started it. If the server is started by another user later there is a chance that one or more AUTOFOCUS document files can't be read by this user. Also the client had to be restarted after deleting two documents out of a project.

5.2 Subsumption of Autofocus strengths and weaknesses

AUTOFOCUS has its strengths and weaknesses. We appreciated the visualisation of the specification. The graphs of the system structure diagrams and the state transition diagrams look good, with only a few "styling" mouse clicks. You get an image of what the system does in a short time. Also AUTOFOCUS uses only a few graphical elements (states and state transitions, structures and channels) and thus the graphs are not "visually overloaded".

A further big advantage of AUTOFOCUS is that you can do a quite raw design of your specification at first. You can assign general behaviours to components to get a superficial realisation. Then you can "deepen" the specification by assigning subcomponents to components. This works also with state transition diagrams, where you can assign sub-states to existing states.

Also AUTOFOCUS had some nasty weaknesses: Signals that are required by a lot of components (e.g. the timer of the tamagotchi component clock), have to be passed to each component by a separate channel. This can lead to a confusing visualisation. Another feature is the lacking of some timer objects. It is hard to realize realtime systems, because all you can do is a clock that is step based. The speed such a clock is based on the performance of the simulation computer you use. The menus of AUTOFOCUS didn't support hotkeys for operations that were needed often and editing the diagrams was partly very unintuitive and the cut and paste functions didn't work properly. Also it was sometimes very

annoying to alter a part in a diagram, which has a substructure assigned to it. Alterations aren't passed to referencing parts automatically, it has to be done manually.

5.3 Proposal of how to improve Notation, Tool and AUTOFOCUS

After specifying a rather complex system, like the tamagotchi, in autofocus, we have a few proposals how to improve and expand the method and the tool.

The Method should be expanded with two new features: a reset signal for the automata and a bus object. A reset signal is very useful for big state transition diagrams: if there is a reset, the reset signal is set only for one clock step. So you have to check for a reset signal in every state of the automaton and you have a reset transition out of every state of it. While this is correct from the automaton theory point of view, it makes a large state transition diagram confusing. It would increase the readability of such a diagram, if you could define one reset-signal for this automaton, which when it is triggered puts the automaton into a certain state after executing a certain transition. The other valuable expansion would be a bus object. If a signal is needed by a lot of components, it has to be passed to every component by a separate channel. This can render a system structure diagram rather confusing. With the help of a bus object you could pass the signal to all components which are connected to this object.

As the tool is still under development, we have a lot of proposals what should be included or expanded: First of all the most important thing that AUTOFOCUS lacks is a real documentation. It should contain general instructions for the tool and a known bug list. Also it should include multiple small and easy to understand examples, sorted by theme. It would save much time if you could look for a how do I put a variable value into a channel-example, instead of endless trial and error or hidden feature searching. Maybe this can be done in the style of a tutorial with several lessons.

Another important issue is the way AUTOFOCUS manages and saves the data. By now it saves data document based. Many problems could be solved if data storage is done object oriented e.g. changes of variable or channel names could be passed to referencing objects automatically or already existing substructures can be assigned to a new structure. Also it would eliminate another problem we had. Transitions are referenced by their whole data, including the test description: so if a transition in a substructure has only one space character more in its text description, than its equivalent in the structure above, this would lead to an error in the simulation.

Furthermore AUTOFOCUS should do some error checking directly after entering data. This should be done for variable, channel and port names. So that one can eliminate typos immediately without trying to compile the whole specification every time.

5.4 Usefulness of the Modelling and AUTOFOCUS

We think that using a case tool to develop the tamagotchi consumed more time than just to do a general specification and then code it in a programming language. One of the advantages of doing the tamagotchi with a case tool and as a team was, that you look into the specification more often, to ensure that you are doing right and that your parts still fit to the pieces that are done by your teammates. In general we would say, modelling the tamagotchi with autofocus led to a better understanding of the specification. Another advantage is, that a specification that is modelled with a case tool, is much more easy to understand than just code. Once you get used to a modelling type and a tool, the benefits will usually surpass the disadvantages. The last big advantage was the simulation environment, which enabled us to test sub parts of the specification for bugs, before testing the whole specification. As a resume we could say that using a flowchart to develop

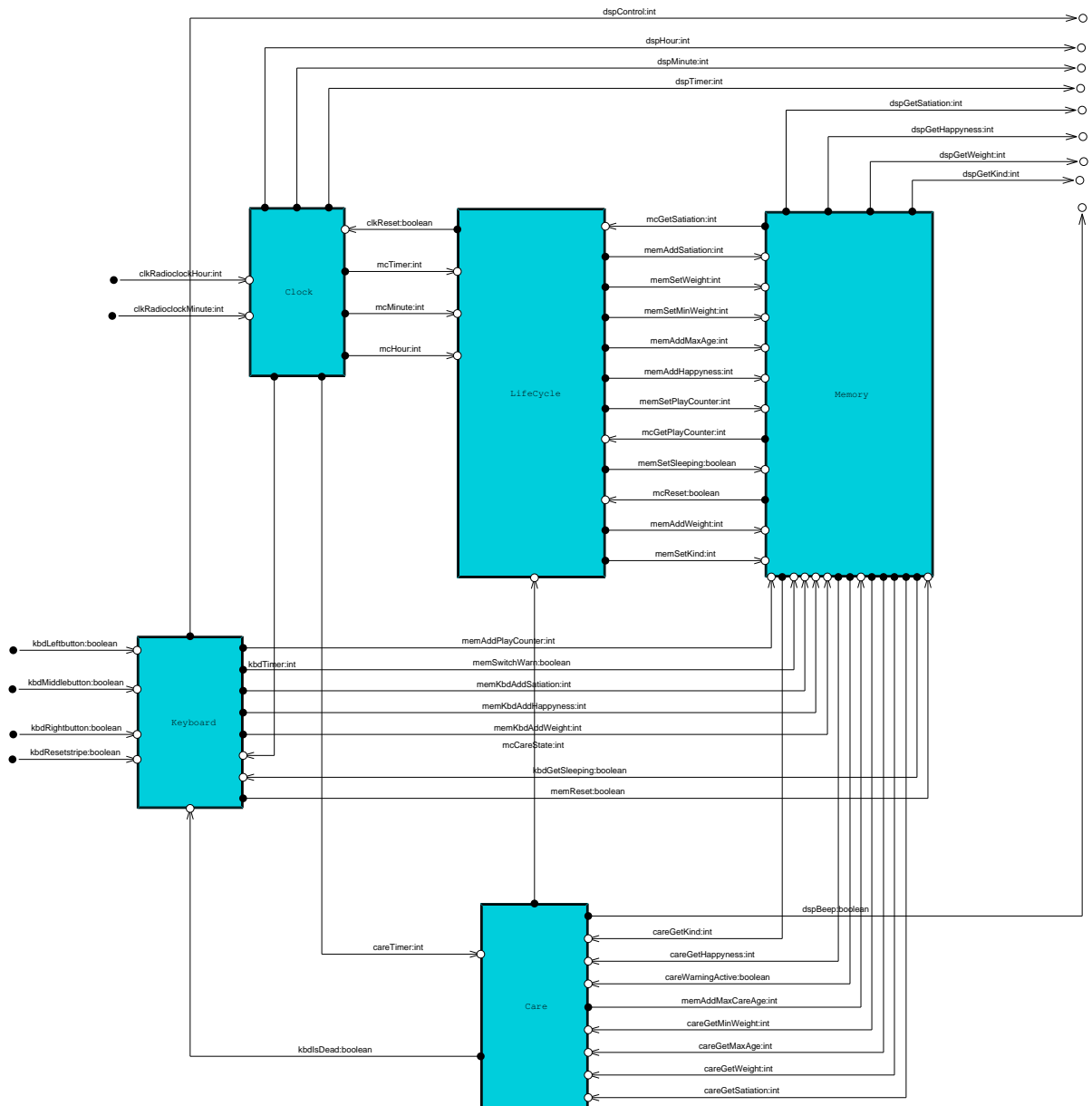
the model of the system and then programming it may have been faster. But for testing the system for correctness, and making it understandable for others AUTOFOCUS did a good job.

5.5 Use AUTOFOCUS again?

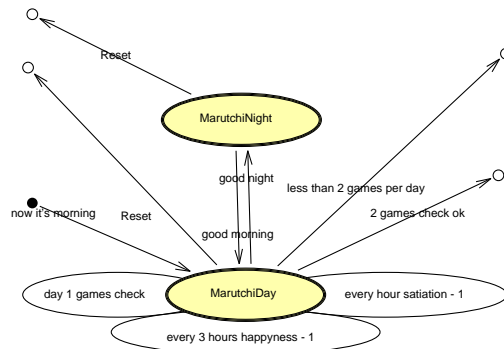
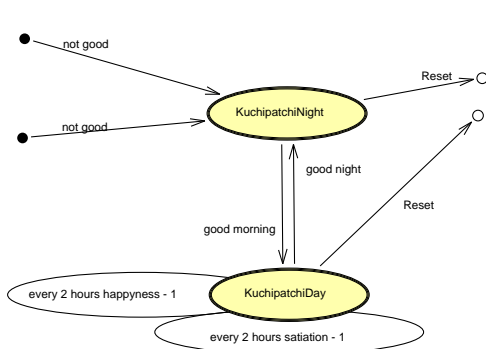
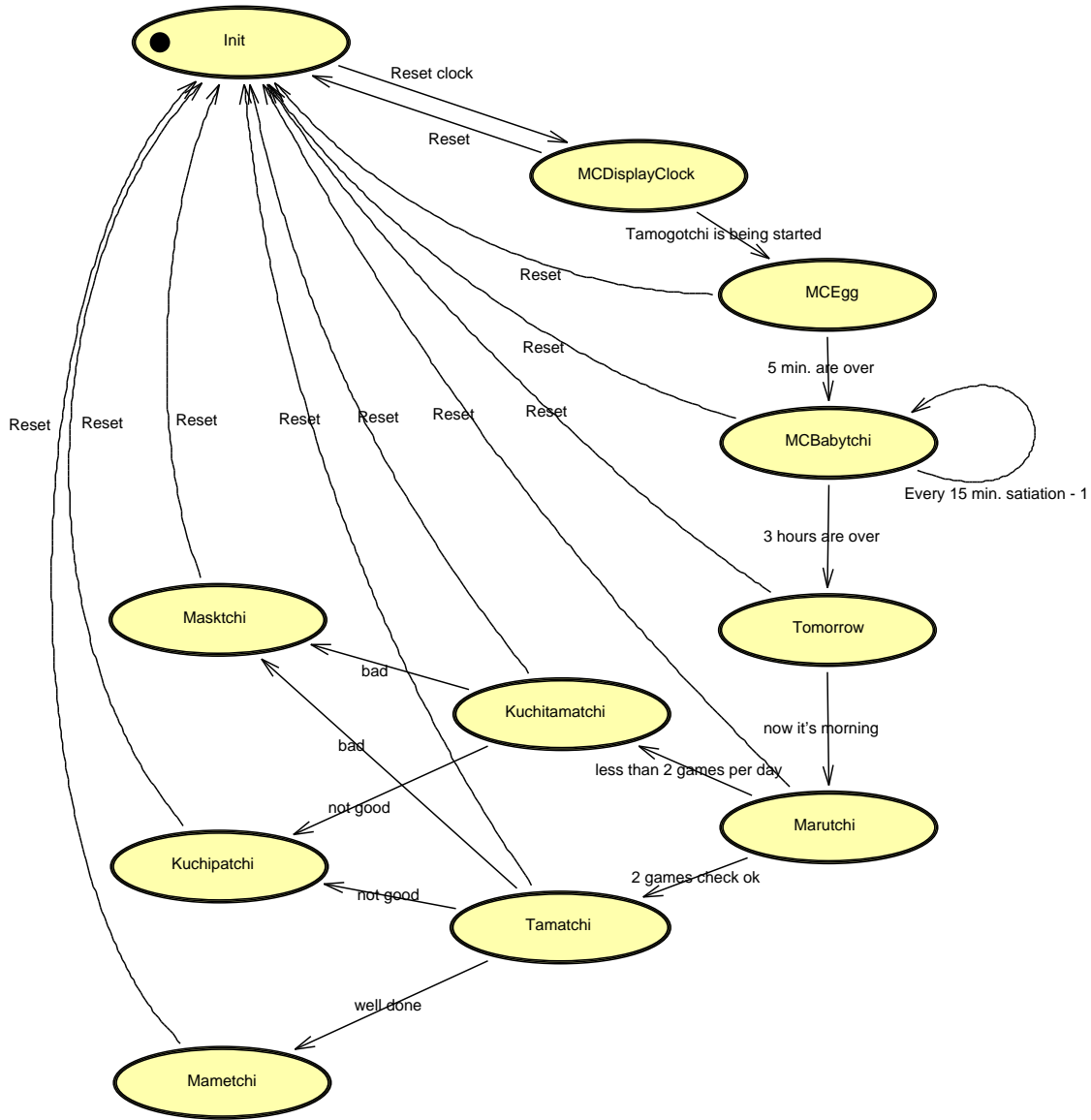
Once we got used to AUTOFOCUS, with its peculiarities, the work progress was good. We would use AUTOFOCUS again, if some bugs would be eliminated. We think that this tool should be developed further, and with a good documentation and a tutorial the time costs for trial and error development with AUTOFOCUS would decrease noticeably.

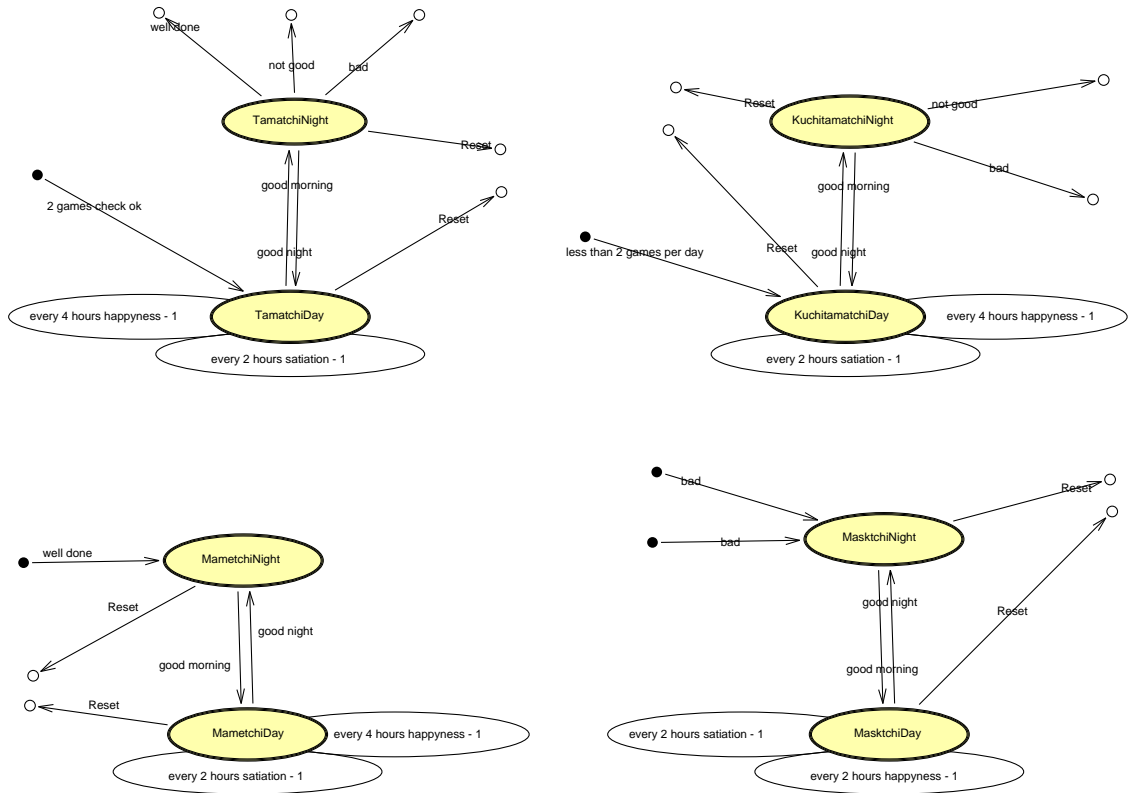
6 Appendix

6.1 Tamagotchi



6.2 Lifecycle





MCDisplayClock \Rightarrow MCEgg Tamogotchi is being started	
Precondition	
Input	mcTimer?T, mcReset?false
Output	dspMCState!2
Postcondition	SleepTimer = T

MCEgg \Rightarrow MCBabytchi 5 min. are over	
Precondition	st \geq SleepTimer + 5
Input	mcTimer?st
Output	memWeight!5, memMinWeight!5, dspMCState!3, clkReset>true
Postcondition	SatTimer = st; SleepTimer = st

MCBabychi \Rightarrow MCBabychi Every 15 min. satiation - 1	
Precondition	st \geq SatTimer + 15
Input	mcTimer?st
Output	memAddSatiation!-1
Postcondition	SatTimer = st

Init \Rightarrow MCDisplayClock Reset clock	
Precondition	
Input	
Output	clkReset>true, dspMCState!1
Postcondition	

MCBabytchi \implies Tomorrow 3 hours are over	
Precondition	st \geq SleepTimer + 180
Input	mcTimer?st
Output	memSleeping!true, dspMCState!4
Postcondition	

Tomorrow \implies MarutchiMarutchiDay now it's morning	
Precondition	H \geq 9
Input	mcHour?H, mcTimer?T
Output	memSleeping!false, dspMCState!5, memWeight!10, memPlayCounter!0, memMinWeight!10
Postcondition	SatTimer = T; HappyTimer = T; TamaKuchiTimer = T; GameState = 0

MarutchiMarutchiDay \implies TamatchiTamatchiDay 2 games check ok	
Precondition	TT \geq TamaKuchiTimer + 2880 && GameState == 1 && PC \geq 4
Input	mcTimer?TT, mcPlayCounter?PC
Output	dspMCState!7, memWeight!20, memMinWeight!20
Postcondition	SatTimer = TT; HappyTimer = TT; NextStateTimer = TT

MarutchiMarutchiDay \implies KuchitamatchiKuchitamatchiDay less than 2 games per day	
Precondition	TT \geq TamaKuchiTimer + 2880 && (GameState != 1 PC < 4)
Input	mcTimer?TT, mcPlayCounter?PC
Output	dspMCState!9, memWeight!20, memMinWeight!20
Postcondition	SatTimer = TT; HappyTimer = TT; NextStateTimer = TT

TamatchiTamatchiNight \implies KuchipatchiKuchipatchiNight not good	
Precondition	T > NextStateTimer + 7200
Input	mcTimer?T, mcCareState?2
Output	dspMCState!14, memWeight!20, memMinWeight!20, memAddMaxAge!12
Postcondition	SatTimer = T; HappyTimer = T

TamatchiTamatchiNight \implies MasktchiMasktchiNight bad	
Precondition	T > NextStateTimer + 7200
Input	mcTimer?T, mcCareState?3
Output	dspMCState!16, memWeight!30, memMinWeight!30, memAddMaxAge!18
Postcondition	SatTimer = T; HappyTimer = T

KuchitamatchiKuchitamatchiNight \Rightarrow KuchipatchiKuchipatchiNight not good	
Precondition	$T > \text{NextStateTimer} + 7200 \ \&\& \ C \leq 2$
Input	$\text{mcTimer?T}, \ \text{mcCareState?C}$
Output	$\text{dspMCState!14}, \ \text{memWeight!20}, \ \text{memMinWeight!20}, \ \text{memAddMaxAge!12}$
Postcondition	$\text{SatTimer} = T; \ \text{HappyTimer} = T$

KuchitamatchiKuchitamatchiNight \Rightarrow MasktchiMasktchiNight bad	
Precondition	$T > \text{NextStateTimer} + 7200$
Input	$\text{mcTimer?T}, \ \text{mcCareState?3}$
Output	$\text{dspMCState!16}, \ \text{memWeight!30}, \ \text{memMinWeight!30}, \ \text{memAddMaxAge!18}$
Postcondition	$\text{SatTimer} = T; \ \text{HappyTimer} = T$

TamatchiTamatchiNight \Rightarrow MametchiMametchiNight well done	
Precondition	$T > \text{NextStateTimer} + 7200$
Input	$\text{mcTimer?T}, \ \text{mcCareState?1}$
Output	$\text{dspMCState!12}, \ \text{memWeight!30}, \ \text{memMinWeight!30}, \ \text{memAddMaxAge!22}$
Postcondition	$\text{SatTimer} = T; \ \text{HappyTimer} = T$

MCDisplayClock \Rightarrow Init Reset	
Precondition	
Input	mcReset?true
Output	
Postcondition	

MCEgg \Rightarrow Init Reset	
Precondition	
Input	mcReset?true
Output	
Postcondition	

MCBabytchi \Rightarrow Init Reset	
Precondition	
Input	mcReset?true
Output	
Postcondition	

Tomorrow \Rightarrow Init Reset	
Precondition	
Input	mcReset?true
Output	
Postcondition	

MarutchiMarutchiNight \Rightarrow Init Reset	
Precondition Input Output Postcondition	mcReset?true

TamatchiTamatchiNight \Rightarrow Init Reset	
Precondition Input Output Postcondition	mcReset?true

MametchiMametchiDay \Rightarrow Init Reset	
Precondition Input Output Postcondition	mcReset?true

KuchitamatchiKuchitamatchiNight \Rightarrow Init Reset	
Precondition Input Output Postcondition	mcReset?true

KuchipatchiKuchipatchiNight \Rightarrow Init Reset	
Precondition Input Output Postcondition	mcReset?true

MasktchiMasktchiNight \Rightarrow Init Reset	
Precondition Input Output Postcondition	mcReset?true

MarutchiMarutchiDay \Rightarrow MarutchiMarutchiDay Marutchievery 3 hours happiness - 1	
Precondition Input Output Postcondition	ht \geq HappyTimer + 180 mcTimer?ht memAddHappyness!-1 HappyTimer = ht

MarutchiMarutchiDay \Rightarrow MarutchiMarutchiDay Marutchievery hour satiation - 1	
Precondition	st \geq SatTimer + 60
Input	mcTimer?st
Output	memAddSatiation!-1
Postcondition	SatTimer = st

MarutchiMarutchiDay \Rightarrow MarutchiMarutchiNight Marutchigood night	
Precondition	h < 9 h \geq 20
Input	mcHour?h
Output	memSleeping!true, dspMCState!6
Postcondition	

MarutchiMarutchiNight \Rightarrow MarutchiMarutchiDay Marutchigood morning	
Precondition	h \geq 9 && h < 20
Input	mcHour?h
Output	memSleeping!false, dspMCState!5, memAddWeight!-2
Postcondition	

MarutchiMarutchiDay \Rightarrow MarutchiMarutchiDay Marutchiday 1 games check	
Precondition	TT \geq TamaKuchiTimer + 1440 && GameState == 0 && PC \geq 2
Input	mcTimer?TT, mcPlayCounter?PC
Output	
Postcondition	GameState = 1

TamatchiTamatchiDay \Rightarrow TamatchiTamatchiDay Tamatchievery 2 hours satiation - 1	
Precondition	st \geq SatTimer + 120
Input	mcTimer?st
Output	memAddSatiation!-1
Postcondition	SatTimer = st

TamatchiTamatchiDay \Rightarrow TamatchiTamatchiDay Tamatchievery 4 hours happyness - 1	
Precondition	ht \geq HappyTimer + 240
Input	mcTimer?ht
Output	memAddHappyness!-1
Postcondition	HappyTimer = ht

TamatchiTamatchiDay \Rightarrow TamatchiTamatchiNight Tamatchigood night	
Precondition	h < 9 h \geq 21
Input	mcHour?h
Output	memSleeping!true, dspMCState!8
Postcondition	

TamatchiTamatchiNight \Rightarrow TamatchiTamatchiDay Tamatchigood morning	
Precondition	$h \geq 9 \ \&\& \ h < 21$
Input	mcHour?h
Output	memSleeping!false, dspMCState!7, memAddWeight!-4
Postcondition	

KuchitamatchiKuchitamatchiDay \Rightarrow KuchitamatchiKuchitamatchiDay Kuchitamatchievery 2 hours satiation - 1	
Precondition	$st \geq \text{SatTimer} + 120$
Input	mcTimer?st
Output	memAddSatiation!-1
Postcondition	SatTimer = st

KuchitamatchiKuchitamatchiDay \Rightarrow KuchitamatchiKuchitamatchiDay Kuchitamatchievery 4 hours happyness - 1	
Precondition	$ht \geq \text{HappyTimer} + 240$
Input	mcTimer?ht
Output	memAddHappyness!-1
Postcondition	HappyTimer = ht

KuchitamatchiKuchitamatchiDay \Rightarrow KuchitamatchiKuchitamatchiNight Kuchitamatchigood night	
Precondition	$h < 9 \ \ h \geq 21$
Input	mcHour?h
Output	memSleeping!true, dspMCState!10
Postcondition	

KuchitamatchiKuchitamatchiNight \Rightarrow KuchitamatchiKuchitamatchiDay Kuchitamatchigood morning	
Precondition	$h \geq 9 \ \&\& \ h < 21$
Input	mcHour?h
Output	memSleeping!false, dspMCState!9, memAddWeight!-4
Postcondition	

MametchiMametchiDay \Rightarrow MametchiMametchiDay Mametchievery 2 hours satiation - 1	
Precondition	$st \geq \text{SatTimer} + 120$
Input	mcTimer?st
Output	memAddSatiation!-1
Postcondition	SatTimer = st

MametchiMametchiDay \Rightarrow MametchiMametchiDay Mametchievery 4 hours happyness - 1	
Precondition	$ht \geq \text{HappyTimer} + 240$
Input	mcTimer?ht
Output	memAddHappyness!-1
Postcondition	HappyTimer = ht

MametchiMametchiDay \implies MametchiMametchiNight Mametchigood night	
Precondition	$h < 10 \parallel h \geq 21$
Input	mcHour?h
Output	memSleeping!true, dspMCState!12
Postcondition	

MametchiMametchiNight \implies MametchiMametchiDay Mametchigood morning	
Precondition	$h \geq 10 \ \&\& \ h < 21$
Input	mcHour?h
Output	memSleeping!false, dspMCState!11, memAddWeight!-6
Postcondition	

KuchipatchiKuchipatchiDay \implies KuchipatchiKuchipatchiDay Kuchipatchievery 2 hours satiation - 1	
Precondition	$st \geq \text{SatTimer} + 120$
Input	mcTimer?st
Output	memAddSatiation!-1
Postcondition	SatTimer = st

KuchipatchiKuchipatchiDay \implies KuchipatchiKuchipatchiDay Kuchipatchievery 2 hours happyness - 1	
Precondition	$ht \geq \text{HappyTimer} + 120$
Input	mcTimer?ht
Output	memAddHappyness!-1
Postcondition	HappyTimer = ht

KuchipatchiKuchipatchiDay \implies KuchipatchiKuchipatchiNight Kuchipatchigood night	
Precondition	$h < 10 \parallel h \geq 21$
Input	mcHour?h
Output	memSleeping!true, dspMCState!14
Postcondition	

KuchipatchiKuchipatchiNight \implies KuchipatchiKuchipatchiDay Kuchipatchigood morning	
Precondition	$h \geq 10 \ \&\& \ h < 21$
Input	mcHour?h
Output	memSleeping!false, dspMCState!13, memAddWeight!-6
Postcondition	

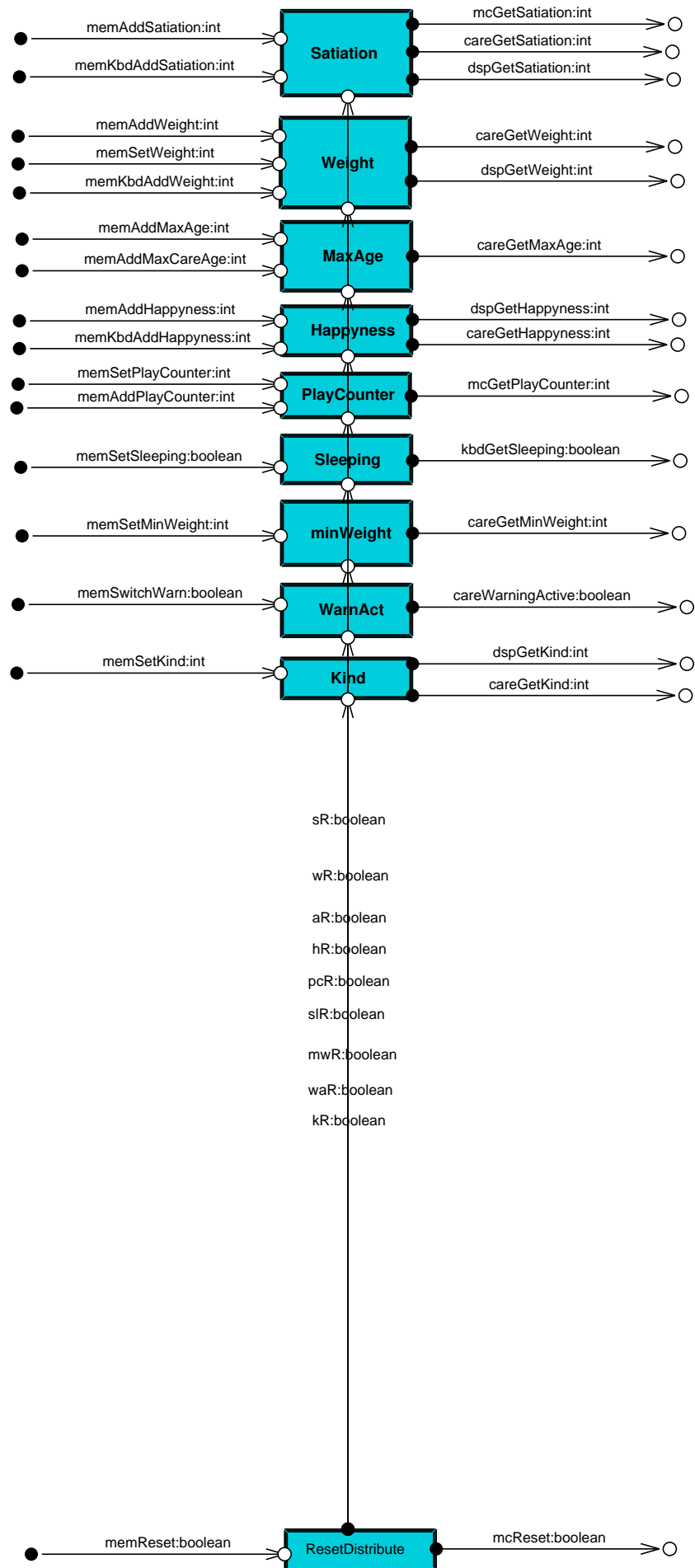
MasktchiMasktchiDay \implies MasktchiMasktchiDay Masktchievery 2 hours happyness - 1	
Precondition	$ht \geq \text{HappyTimer} + 120$
Input	mcTimer?ht
Output	memAddHappyness!-1
Postcondition	HappyTimer = ht

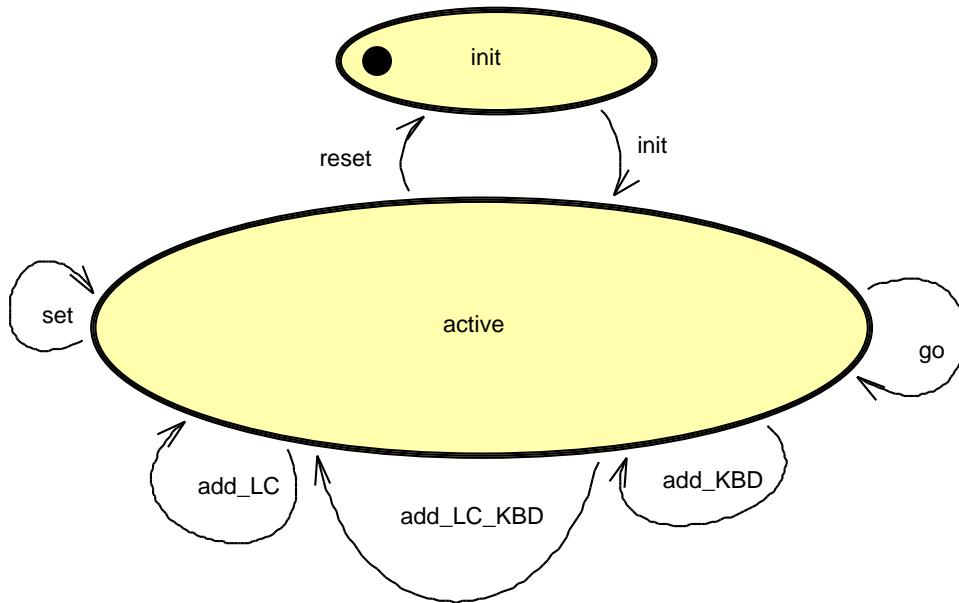
MasktchiMasktchiDay \implies MasktchiMasktchiDay Masktchievery 2 hours satiation - 1	
Precondition	st \geq SatTimer + 120
Input	mcTimer?st
Output	memAddSatiation!-1
Postcondition	SatTimer = st

MasktchiMasktchiDay \implies MasktchiMasktchiNight Masktchigood night	
Precondition	h < 11 h \geq 23
Input	mcHour?h
Output	memSleeping!true, dspMCState!16
Postcondition	

MasktchiMasktchiNight \implies MasktchiMasktchiDay Masktchigood morning	
Precondition	h \geq 11 && h < 23
Input	mcHour?h
Output	memSleeping!false, dspMCState!15, memAddWeight!-6
Postcondition	

6.3 Memory





active \Rightarrow active go	
Precondition	
Input	memAddWeight?, memKbdAddWeight?, wR?, mem-
Output	SetWeight?
Postcondition	dspGetWeight!Value, careGetWeight!Value

init \Rightarrow active init	
Precondition	
Input	
Output	dspGetWeight!0, careGetWeight!0
Postcondition	Value = 0

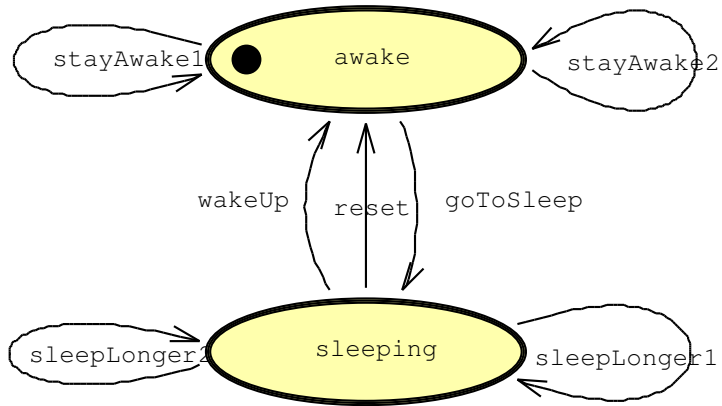
active \Rightarrow active add_LC	
Precondition	
Input	memAddWeight?temp, memKbdAddWeight?, wR?, mem-
Output	SetWeight?
Postcondition	dspGetWeight!Value, careGetWeight!Value Value = Value + temp

active \Rightarrow init reset	
Precondition	
Input	wR?true
Output	dspGetWeight!0, careGetWeight!0
Postcondition	Value = 0

active \Rightarrow active set	
Precondition	
Input	memSetWeight?temp, wR?
Output	careGetWeight!temp, dspGetWeight!temp
Postcondition	Value = temp

active \Rightarrow active add_KBD	
Precondition	
Input	memKbdAddWeight?temp, memAddWeight?, wR?, mem-SetWeight?
Output	dspGetWeight!Value, careGetWeight!Value
Postcondition	Value = Value + temp

active \Rightarrow active add_LC_KBD	
Precondition	
Input	memAddWeight?temp1, memKbdAddWeight?temp2, wR?, memSetWeight?
Output	dspGetWeight!Value, careGetWeight!Value
Postcondition	Value = Value + temp1 + temp2



awake \Rightarrow sleeping
goToSleep

Precondition
Input
Output
Postcondition

memSetSleeping?true, slR?
kbdGetSleeping!true

sleeping \Rightarrow awake wakeUp	
Precondition Input Output Postcondition	memSetSleeping?false kbdGetSleeping!false

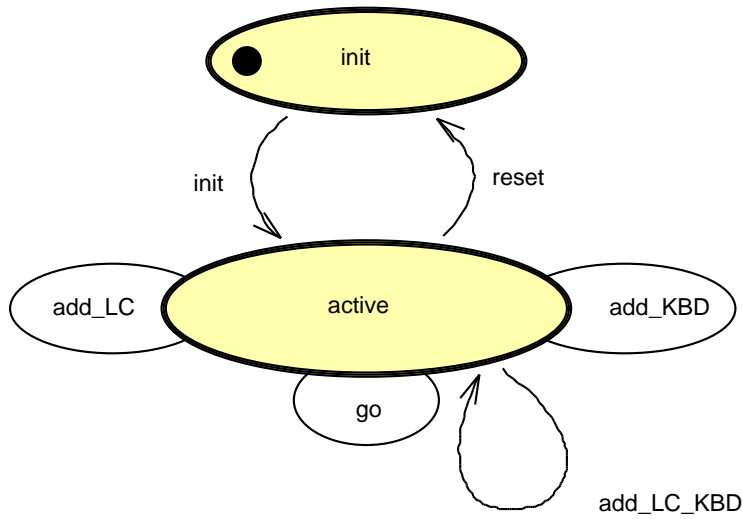
awake \Rightarrow awake stayAwake1	
Precondition Input Output Postcondition	memSetSleeping? kbdGetSleeping!false

awake \Rightarrow awake stayAwake2	
Precondition Input Output Postcondition	memSetSleeping?false kbdGetSleeping!false

sleeping \Rightarrow sleeping sleepLonger1	
Precondition Input Output Postcondition	memSetSleeping?, slR? kbdGetSleeping!true

sleeping \Rightarrow sleeping sleepLonger2	
Precondition Input Output Postcondition	slR?, memSetSleeping?true kbdGetSleeping!true

sleeping \Rightarrow awake reset	
Precondition Input Output Postcondition	slR?true kbdGetSleeping!false



active \Rightarrow active go	
Precondition	
Input	memAddSatiatiion?, memKbdAddSatiatiion?, sR?
Output	mcGetSatiatiion!Value, dspGetSatiatiion!Value, careGetSatiatiion!Value
Postcondition	

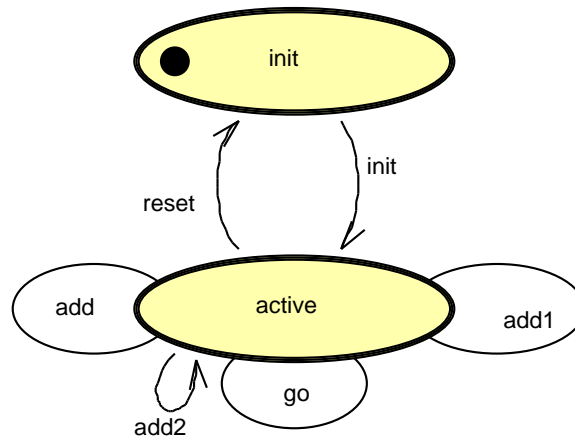
init \Rightarrow active init	
Precondition	
Input	
Output	mcGetSatiatiion!4, dspGetSatiatiion!4, careGetSatiatiion!4
Postcondition	Value = 4

active \Rightarrow active add_LC	
Precondition	
Input	memAddSatiatiion?temp, memKbdAddSatiatiion?, sR?
Output	mcGetSatiatiion!Value, dspGetSatiatiion!Value, careGetSatiatiion!Value
Postcondition	Value = Value + temp

active \Rightarrow init reset	
Precondition	
Input	sR?true
Output	dspGetSatiatiion!4, mcGetSatiatiion!4, careGetSatiatiion!4
Postcondition	Value = 4

active \Rightarrow active add_KBD	
Precondition	
Input	memKbdAddSatiation?temp, memAddSatiation?, sR?
Output	mcGetSatiation!Value, careGetSatiation!Value, dspGetSatiation!Value
Postcondition	Value = Value + temp

active \Rightarrow active add_LC_KBD	
Precondition	
Input	memAddSatiation?temp1, memKbdAddSatiation?temp2, sR?
Output	mcGetSatiation!Value, careGetSatiation!Value, dspGetSatiation!Value
Postcondition	Value = Value + temp1 + temp2



active \Rightarrow active go	
Precondition	
Input	memAddMaxAge?, memAddMaxCareAge?, aR?
Output	careGetMaxAge!Value
Postcondition	

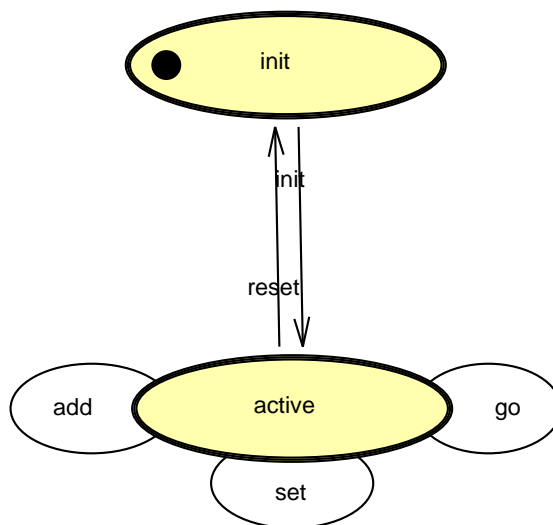
init \Rightarrow active init	
Precondition	
Input	
Output	careGetMaxAge!0
Postcondition	Value = 0

active \Rightarrow active add	
Precondition	
Input	memAddMaxAge?temp, memAddMaxCareAge?, aR?
Output	careGetMaxAge!Value
Postcondition	Value = Value + temp

active \Rightarrow init reset	
Precondition	
Input	aR?true
Output	careGetMaxAge!0
Postcondition	Value = 0

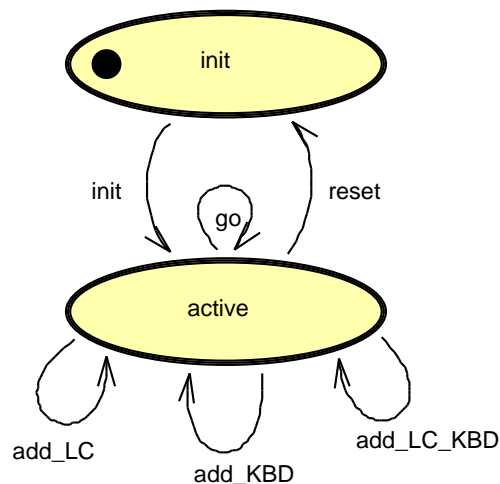
active \Rightarrow active add1	
Precondition	
Input	memAddMaxCareAge?temp, aR?, memAddMaxAge?
Output	careGetMaxAge!Value
Postcondition	Value = Value + temp

active \Rightarrow active add2	
Precondition	
Input	memAddMaxAge?temp1, memAddMaxCareAge?temp2, aR?
Output	careGetMaxAge!Value
Postcondition	Value = Value + temp1 + temp2



init \Rightarrow active init	
Precondition	
Input	
Output	mcGetPlayCounter!0
Postcondition	Value = 0

active \Rightarrow init reset	
Precondition	
Input	pcR?true
Output	mcGetPlayCounter!0
Postcondition	Value = 0
active \Rightarrow active set	
Precondition	
Input	memSetPlayCounter?temp, pcR?
Output	mcGetPlayCounter!temp
Postcondition	Value = temp
active \Rightarrow active go	
Precondition	
Input	memSetPlayCounter?, pcR?, memAddPlayCounter?
Output	mcGetPlayCounter!Value
Postcondition	
active \Rightarrow active add	
Precondition	
Input	memAddPlayCounter?temp, pcR?, memSetPlayCounter?
Output	mcGetPlayCounter!Value
Postcondition	Value = Value + temp



active \Rightarrow active go	
Precondition	
Input	hR?, memAddHappyness?, memKbdAddHappyness?
Output	dspGetHappyness!Value, careGetHappyness!Value
Postcondition	

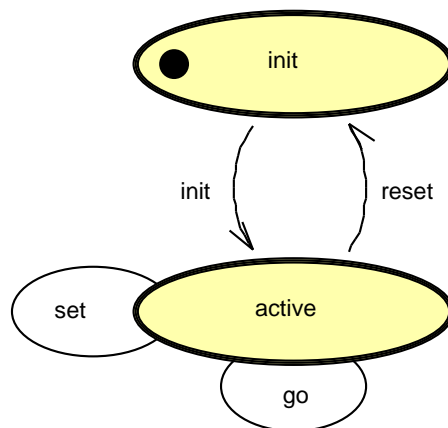
init \Rightarrow active init	
Precondition	
Input	
Output	dspGetHappyness!4, careGetHappyness!4
Postcondition	Value = 4

active \Rightarrow active add_LC	
Precondition	
Input	memAddHappyness?temp, memKbdAddHappyness?, hR?
Output	careGetHappyness!Value, dspGetHappyness!Value
Postcondition	Value = Value + temp

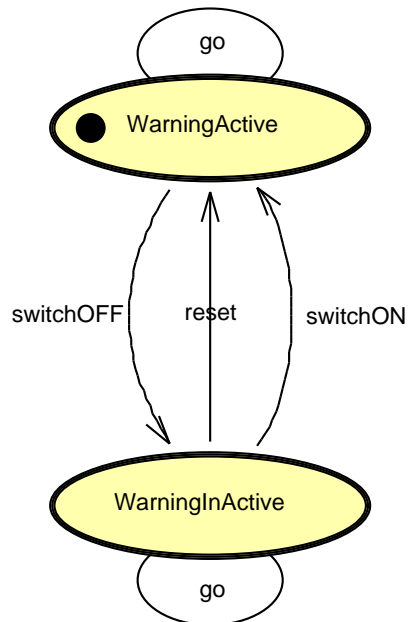
active \Rightarrow init reset	
Precondition	
Input	hR?true
Output	dspGetHappyness!4, careGetHappyness!4
Postcondition	Value = 4

active \Rightarrow active add_KBD	
Precondition	
Input	memKbdAddHappyness?temp, memAddHappyness?, hR?
Output	careGetHappyness!Value, dspGetHappyness!Value
Postcondition	Value = Value + temp

active \Rightarrow active add_LC_KBD	
Precondition	
Input	memKbdAddHappyness?temp1, memAddHappyness?temp2, hR?
Output	careGetHappyness!Value, dspGetHappyness!Value
Postcondition	Value = Value + temp1 + temp2



active \Rightarrow active go	
Precondition	
Input	mwR?, memSetMinWeight?
Output	careGetMinWeight!Value
Postcondition	
init \Rightarrow active init	
Precondition	
Input	
Output	careGetMinWeight!0
Postcondition	Value = 0
active \Rightarrow active set	
Precondition	
Input	memSetMinWeight?temp, mwR?
Output	careGetMinWeight!temp
Postcondition	Value = temp
active \Rightarrow init reset	
Precondition	
Input	mwR?true
Output	careGetMinWeight!0
Postcondition	Value = 0



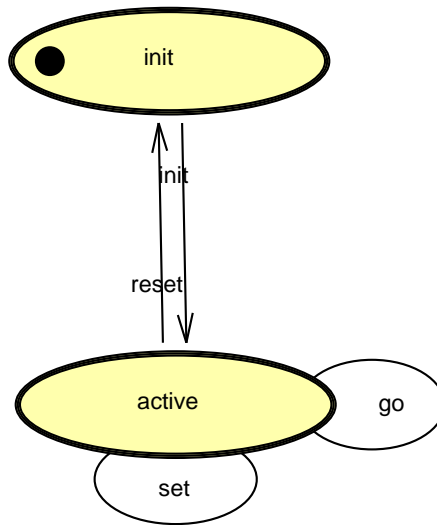
WarningInactive \Rightarrow WarningActive reset	
Precondition	
Input	waR?true
Output	careWarningActive!true
Postcondition	

WarningActive \Rightarrow WarningInactive switchOFF	
Precondition	
Input	memSwitchWarn?true, waR?
Output	careWarningActive!false
Postcondition	

WarningInactive \Rightarrow WarningActive switchON	
Precondition	
Input	memSwitchWarn?true, waR?
Output	careWarningActive!true
Postcondition	

WarningActive \Rightarrow WarningActive go	
Precondition	
Input	memSwitchWarn?
Output	careWarningActive!true
Postcondition	

WarningInactive \Rightarrow WarningInactive go	
Precondition	
Input	waR?, memSwitchWarn?
Output	careWarningActive!false
Postcondition	

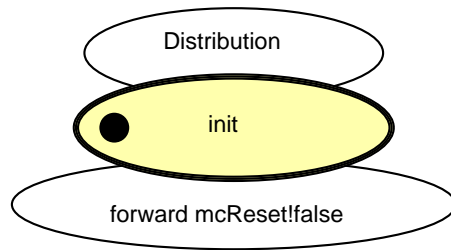


init \Rightarrow active init	
Precondition	
Input	
Output	dspGetKind!1, careGetKind!1
Postcondition	Value = 1

active \Rightarrow init reset	
Precondition	
Input	kR?true
Output	dspGetKind!1, careGetKind!1
Postcondition	Value = 1

active \Rightarrow active set	
Precondition	
Input	memSetKind?temp, kR?
Output	dspGetKind!temp, careGetKind!temp
Postcondition	Value = temp

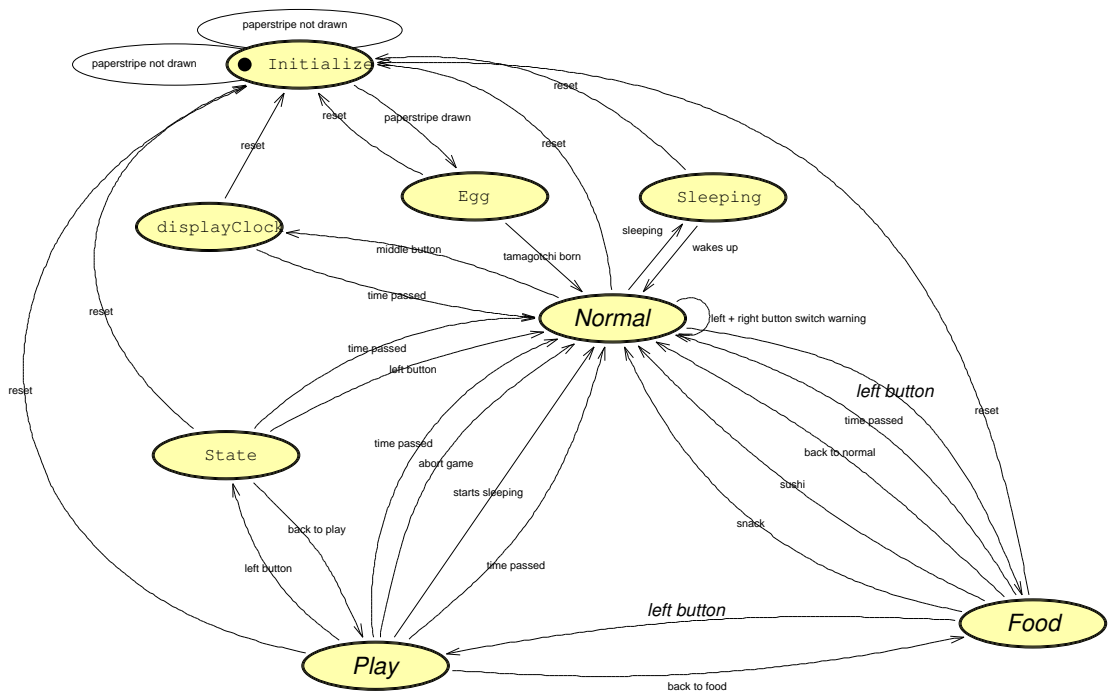
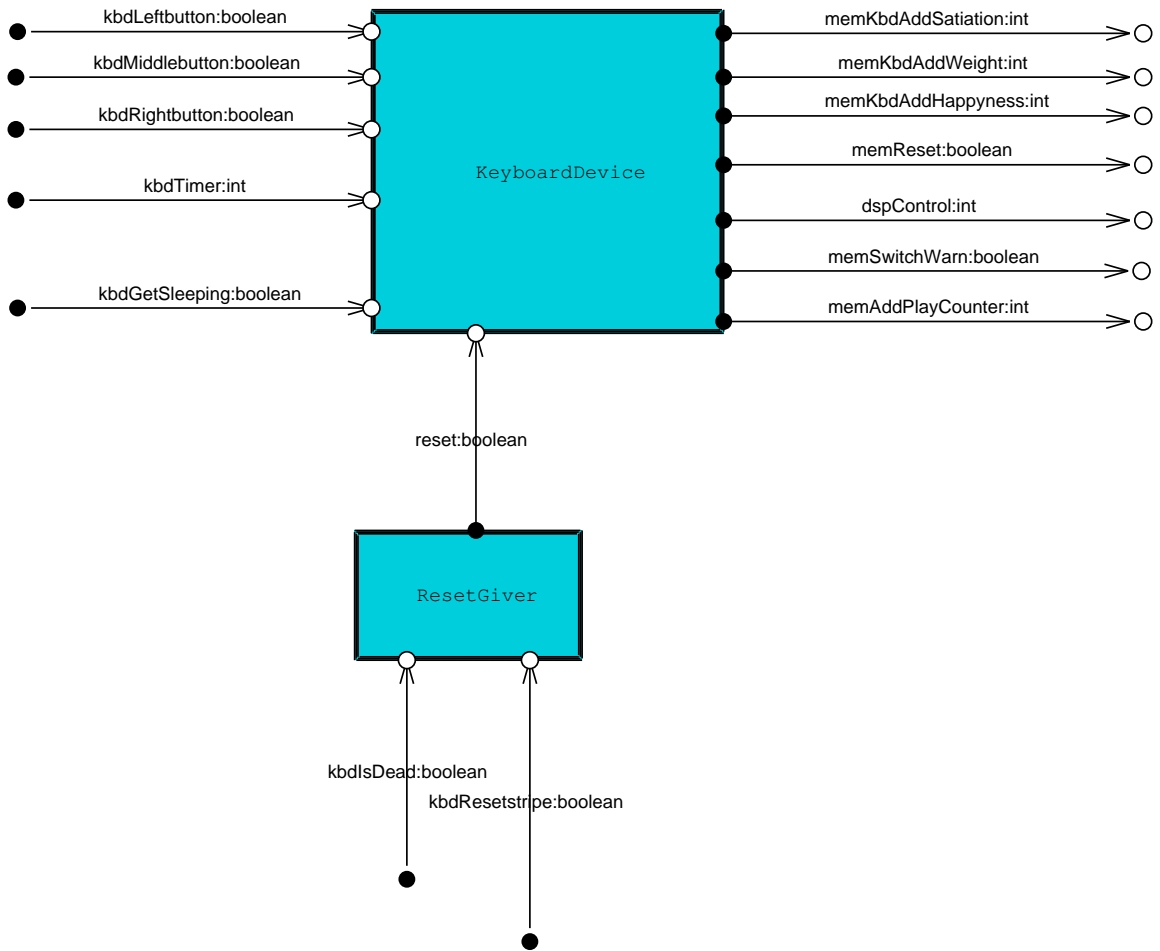
active \Rightarrow active go	
Precondition	
Input	memSetKind?, kR?
Output	dspGetKind!Value, careGetKind!Value
Postcondition	

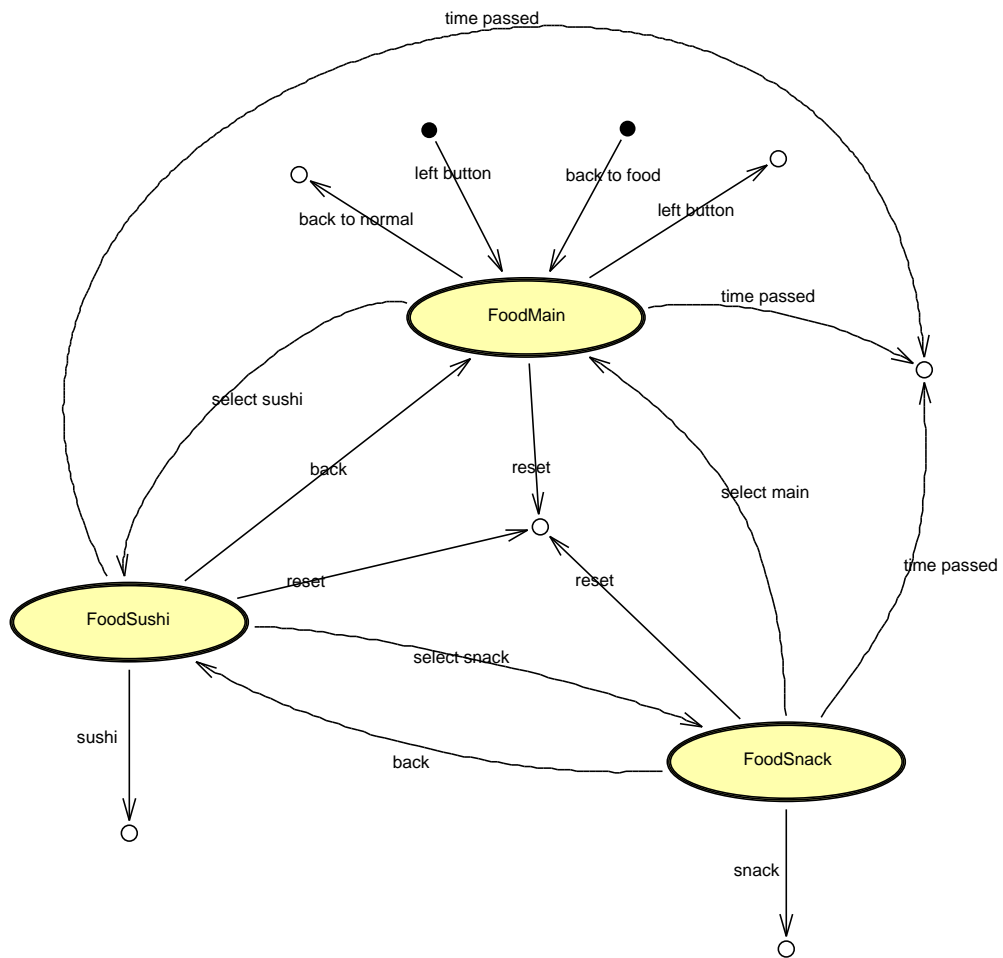


init \Rightarrow init Distribution	
Precondition	
Input	memReset?true
Output	sR!true, wR!true, aR!true, hR!true, pcR!true, slR!true, mwR!true, mcReset!true, waR!true, kR!true
Postcondition	

init \Rightarrow init forward mcReset!false	
Precondition	
Input	memReset?false
Output	mcReset!false
Postcondition	

6.4 Keyboard





Initialize \Rightarrow Initialize paperstripe not drawn	
Precondition	
Input	reset?true
Output	dspControl!10
Postcondition	

Initialize \Rightarrow Initialize paperstripe not drawn	
Precondition	
Input	reset?
Output	dspControl!10
Postcondition	

Initialize \Rightarrow Egg paperstripe drawn	
Precondition	
Input	reset?false
Output	memReset!false, dspControl!20
Postcondition	

Egg \Rightarrow Initialize reset	
Precondition	
Input	reset?true
Output	memReset!true, dspControl!10
Postcondition	

Egg \Rightarrow Normal tamagotchi born	
Precondition	
Input	kbdTimer?0
Output	
Postcondition	

Normal \Rightarrow Initialize reset	
Precondition	
Input	reset?true
Output	memReset!true, dspControl!10
Postcondition	

Normal \Rightarrow displayClock middle button	
Precondition	
Input	reset?, kbdTimer?x, kbdMiddlebutton?true
Output	dspControl!10
Postcondition	Savetimer=x

displayClock \Rightarrow Normal time passed	
Precondition	x>Savetimer+5
Input	kbdTimer?x
Output	dspControl!20
Postcondition	Savetimer=0

displayClock \Rightarrow Initialize reset	
Precondition	
Input	reset?true
Output	memReset!true, dspControl!10
Postcondition	

Normal \Rightarrow Normal left + right button switch warning	
Precondition	
Input	reset?, kbdLeftbutton?true, kbdRightbutton?true, kbdGetSleeping?false
Output	memSwitchWarn!true
Postcondition	

Normal \Rightarrow FoodFoodMain left button	
Precondition	
Input	reset?, kbdLeftbutton?true, kbdTimer?x, kbdGetSleeping?false
Output	dspControl!30
Postcondition	Savetimer=x

FoodFoodSushi \Rightarrow Normal time passed	
Precondition	x>Savetimer+20
Input	kbdTimer?x
Output	dspControl!20
Postcondition	

FoodFoodSnack \Rightarrow Initialize reset	
Precondition	
Input	reset?true
Output	memReset!true, dspControl!10
Postcondition	

FoodFoodMain \Rightarrow Normal back to normal	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!20
Postcondition	

FoodFoodMain \Rightarrow PlayPlayMain left button	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!40
Postcondition	

PlayPlayMain \Rightarrow FoodFoodMain back to food	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!30
Postcondition	

PlayNewRound \Rightarrow Normal time passed	
Precondition	x>Savetimer+20
Input	reset?, kbdTimer?x
Output	dspControl!20
Postcondition	

Playtamagotchi thinks left \Rightarrow Initialize reset	
Precondition	
Input	reset?true
Output	memReset!true, dspControl!10
Postcondition	

PlayPlayMain \Rightarrow StateStateMain left button	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!50
Postcondition	

StateStateMain \Rightarrow PlayPlayMain back to play	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!40
Postcondition	

StateWeight \Rightarrow Normal time passed	
Precondition	x>Savetimer+20
Input	reset?, kbdTimer?x
Output	dspControl!20
Postcondition	

StateStateMain \Rightarrow Normal left button	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!20
Postcondition	

StateHappyness \Rightarrow Initialize reset	
Precondition	
Input	reset?true
Output	memReset!true, dspControl!10
Postcondition	

Normal \Rightarrow Sleeping sleeping	
Precondition	
Input	reset?, kbdGetSleeping?true
Output	dspControl!21
Postcondition	

Sleeping \Rightarrow Normal wakes up	
Precondition	
Input	kbdGetSleeping?false
Output	dspControl!20
Postcondition	

Sleeping \Rightarrow Initialize reset	
Precondition	
Input	reset?true
Output	memReset!true, dspControl!10
Postcondition	

FoodFoodSushi \Rightarrow Normal sushi	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!20, memKbdAddSatiation!1, memKbdAddWeight!1
Postcondition	

FoodFoodSnack \Rightarrow Normal snack	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!22, memKbdAddHappyness!1, memKbdAddWeight!2
Postcondition	

Playtamagotchi thinks right \implies Normal abort game	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!20
Postcondition	

PlayNewRound \implies Normal time passed	
Precondition	x>Savetimer+50
Input	reset?, kbdTimer?x
Output	dspControl!20
Postcondition	

PlayNewRound \implies Normal starts sleeping	
Precondition	
Input	reset?, kbdGetSleeping?true
Output	dspControl!20
Postcondition	

FoodFoodMain \implies FoodFoodSushi Foodselect sushi	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!31
Postcondition	

FoodFoodSushi \implies FoodFoodSnack Foodselect snack	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!32
Postcondition	

FoodFoodSushi \implies FoodFoodMain Feedback	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!30
Postcondition	

FoodFoodSnack \implies FoodFoodSushi Feedback	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!31
Postcondition	

FoodFoodSnack \Rightarrow FoodFoodMain Foodselect main	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!30
Postcondition	

PlayPlayMain \Rightarrow PlayNewRound Playstart game	
Precondition	
Input	reset?, kbdMiddlebutton?true, kbdTimer?x
Output	dspControl!41
Postcondition	Round=0; RoundsWon=0; Savetimer=x

PlayNewRound \Rightarrow Playtamagotchi thinks left Playthinks left	
Precondition	Round<5
Input	reset?, kbdGetSleeping?false
Output	dspControl!41
Postcondition	

Playtamagotchi thinks left \Rightarrow PlayNewRound Playround won	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!44
Postcondition	Round++; RoundsWon++

Playtamagotchi thinks left \Rightarrow PlayNewRound Playround lost	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!45
Postcondition	Round++

Playtamagotchi thinks right \Rightarrow PlayNewRound Playround lost	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!43
Postcondition	Round++

Playtamagotchi thinks right \Rightarrow PlayNewRound Playround won	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!42
Postcondition	Round++; RoundsWon++

PlayNewRound \Rightarrow Playtamagotchi thinks right Playthinks right	
Precondition	Round<5
Input	reset?, kbdGetSleeping?false
Output	dspControl!41
Postcondition	

PlayNewRound \Rightarrow PlayNewRound Playgame won	
Precondition	Round==5 && RoundsWon>2
Input	reset?, kbdTimer?x, kbdGetSleeping?false
Output	dspControl!41, memKbdAddHappyness!1, memKbdAddWeight!-1, memAddPlayCounter!1
Postcondition	Savetimer=x; Round=0; RoundsWon=0

PlayNewRound \Rightarrow PlayNewRound Playgame lost	
Precondition	Round==5 && RoundsWon<3
Input	reset?, kbdTimer?x, kbdGetSleeping?false
Output	dspControl!41, memKbdAddWeight!-1, memAddPlayCounter!1
Postcondition	Savetimer=x; Round=0; RoundsWon=0;

StateStateMain \Rightarrow StateAge Stateage	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!51
Postcondition	

StateAge \Rightarrow StateStateMain Stateback	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!50
Postcondition	

StateAge \Rightarrow StateWeight Stateweight	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!52
Postcondition	

StateWeight \Rightarrow StateAge Stateback	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!51
Postcondition	

StateWeight \implies StateSatiaton Statesatiaton	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!53
Postcondition	

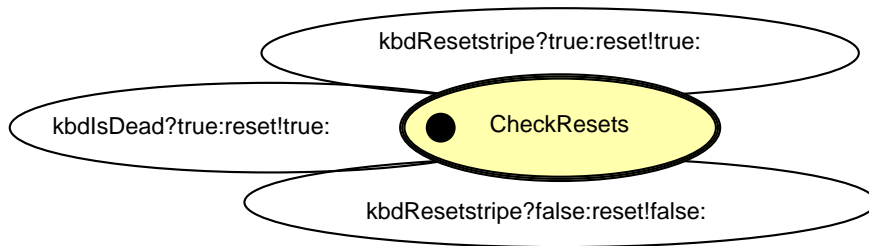
StateSatiaton \implies StateWeight Stateback	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!52
Postcondition	

StateSatiaton \implies StateHappyness Statehappyness	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!54
Postcondition	

StateHappyness \implies StateSatiaton Stateback	
Precondition	
Input	reset?, kbdRightbutton?true
Output	dspControl!53
Postcondition	

StateHappyness \implies StateStateMain Statestatemain L	
Precondition	
Input	reset?, kbdLeftbutton?true
Output	dspControl!50
Postcondition	

StateHappyness \implies StateStateMain Statestatemain M	
Precondition	
Input	reset?, kbdMiddlebutton?true
Output	dspControl!50
Postcondition	

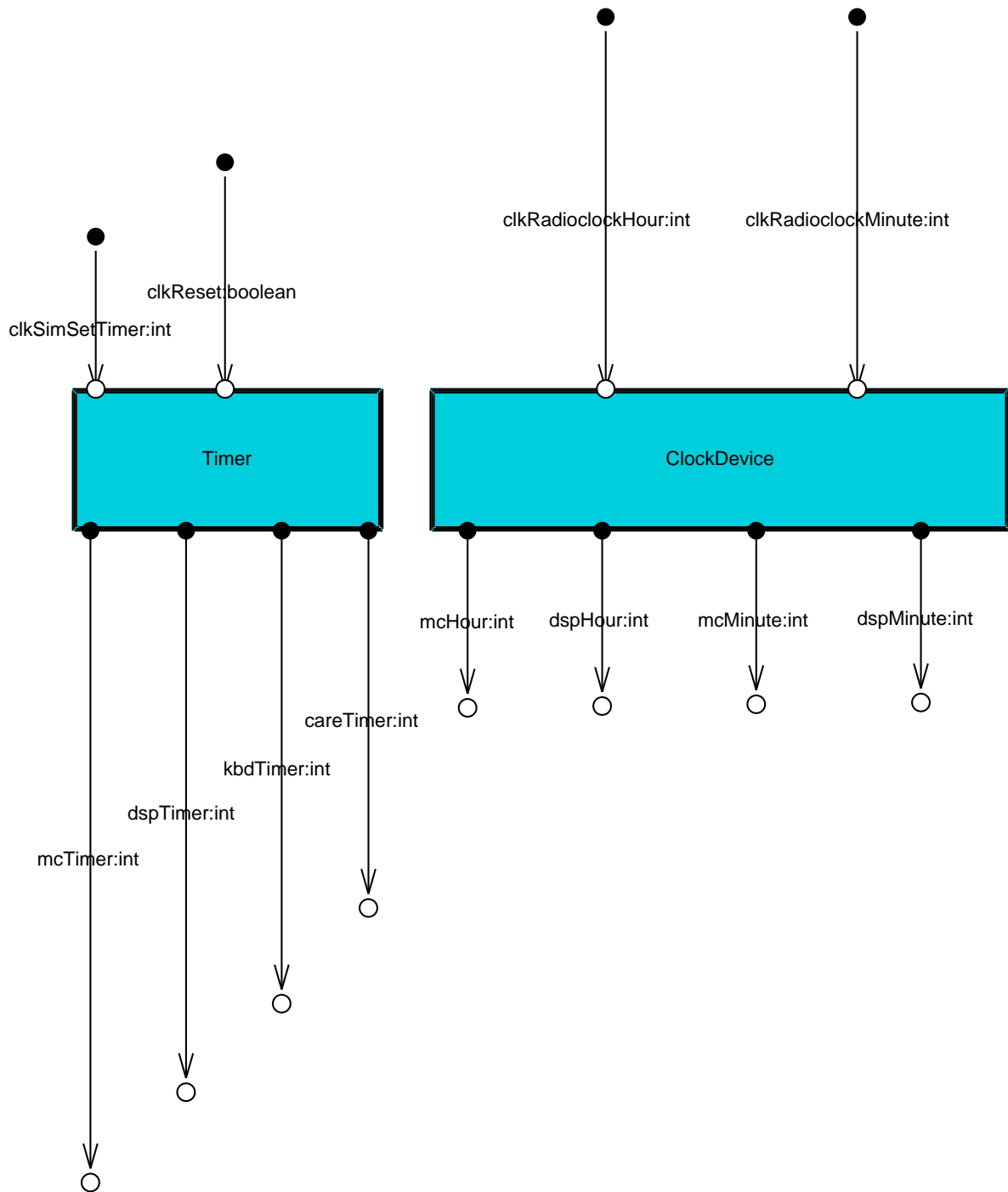


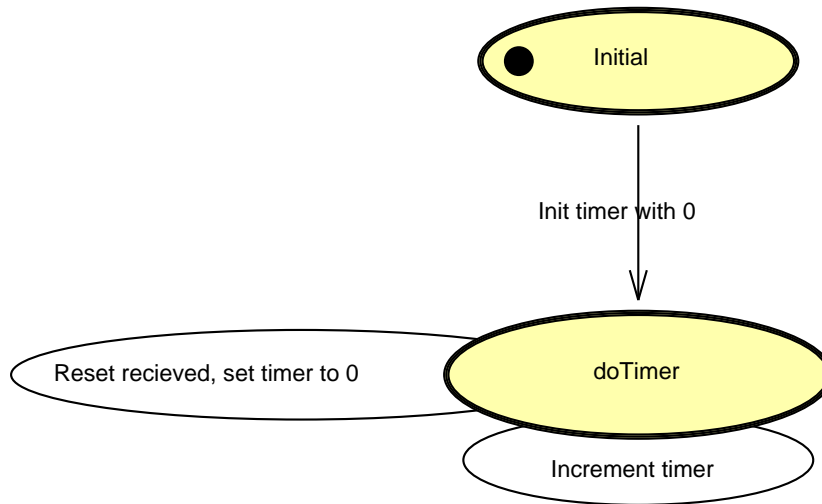
CheckResets \Rightarrow CheckResets kbdResetstripe?true:reset!true:	
Precondition	
Input	kbdResetstripe?true
Output	reset!true
Postcondition	

CheckResets \Rightarrow CheckResets kbdResetstripe?false:reset!false:	
Precondition	
Input	kbdResetstripe?false
Output	reset!false
Postcondition	

CheckResets \Rightarrow CheckResets kbdIsDead?true:reset!true:	
Precondition	
Input	kbdIsDead?true
Output	reset!true
Postcondition	

6.5 Clock

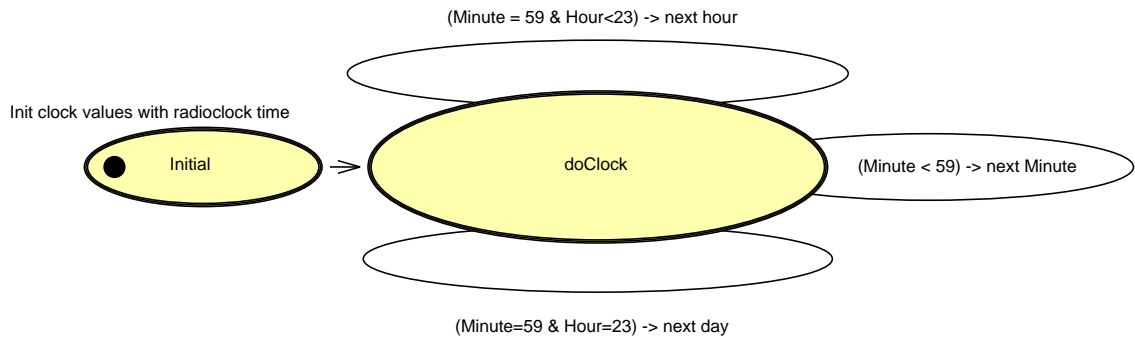




Initial \Rightarrow doTimer Init timer with 0	
Precondition	
Input	
Output	mcTimer!Timervalue, careTimer!Timervalue, dspTi-
Postcondition	mer!Timervalue, kbdTimer!Timervalue Timervalue=0

doTimer \Rightarrow doTimer Increment timer	
Precondition	
Input	clkReset?
Output	mcTimer!Timervalue, careTimer!Timervalue, dspTi-
Postcondition	mer!Timervalue, kbdTimer!Timervalue Timervalue++

doTimer \Rightarrow doTimer Reset recieved, set timer to 0	
Precondition	
Input	clkReset?true
Output	mcTimer!Timervalue, careTimer!Timervalue, dspTi-
Postcondition	mer!Timervalue, kbdTimer!Timervalue Timervalue=0



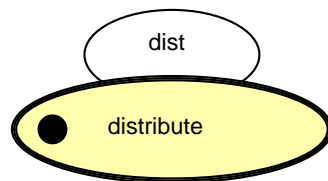
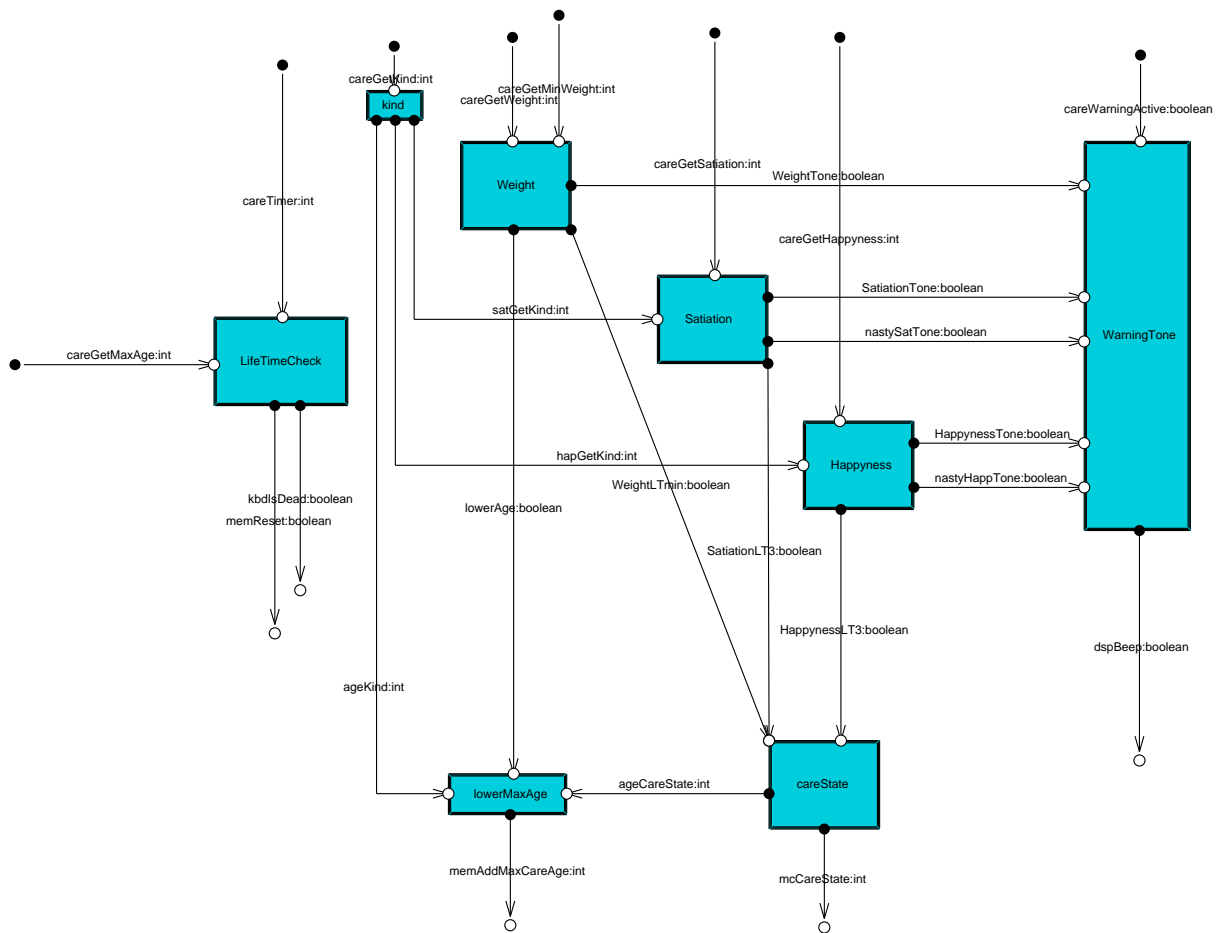
Initial \Rightarrow doClock Init clock values with radioclock time	
Precondition	
Input	clkRadioclockHour?x, clkRadioclockMinute?y
Output	mcHour!Hourvalue, mcMinute!Minutevalue, dspHour!Hourvalue, dspMinute!Minutevalue
Postcondition	Hourvalue=x; Minutevalue=y

doClock \Rightarrow doClock (Minute < 59) -> next Minute	
Precondition	Minutevalue < 59
Input	
Output	mcHour!Hourvalue, mcMinute!Minutevalue, dspHour!Hourvalue, dspMinute!Minutevalue
Postcondition	Minutevalue++

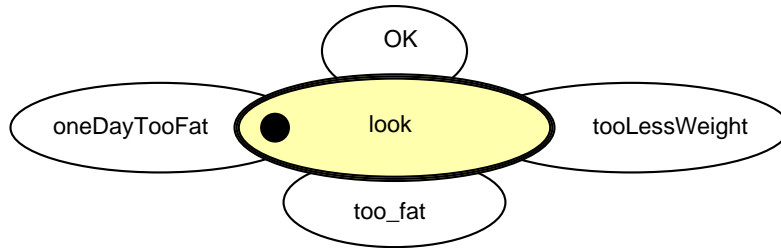
doClock \Rightarrow doClock (Minute = 59 & Hour < 23) -> next hour	
Precondition	Minutevalue==59 && Hourvalue<23
Input	
Output	mcHour!Hourvalue, mcMinute!Minutevalue, dspHour!Hourvalue, dspMinute!Minutevalue
Postcondition	Minutevalue=0; Hourvalue++

doClock \Rightarrow doClock (Minute=59 & Hour=23) -> next day	
Precondition	Minutevalue==59 && Hourvalue == 23
Input	
Output	mcHour!Hourvalue, mcMinute!Minutevalue, dspHour!Hourvalue, dspMinute!Minutevalue
Postcondition	Minutevalue=0; Hourvalue=0

6.6 Care



$\text{distribute} \Rightarrow \text{distribute}$ dist	
Precondition	
Input	<code>careGetKind?x</code>
Output	<code>ageKind!x, hapGetKind!x, satGetKind!x</code>
Postcondition	

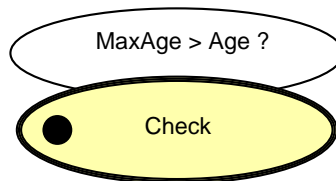


look \Rightarrow look OK	
Precondition	$(2*w < 3*m) \ \&\& \ (w > m)$
Input	careGetWeight?w, careGetMinWeight?m
Output	WeightTone!false, lowerAge!false, WeightLTmin!false
Postcondition	Timer = 1440

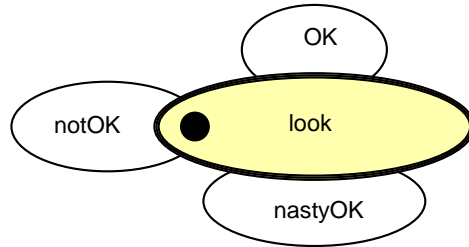
look \Rightarrow look too_fat	
Precondition	$(2*w > 3*m) \ \&\& \ (Timer > 0)$
Input	careGetMinWeight?m, careGetWeight?w
Output	WeightTone!true, lowerAge!false, WeightLTmin!false
Postcondition	Timer = Timer - 1

look \Rightarrow look oneDayTooFat	
Precondition	$(2*w > 3*m) \ \&\& \ (Timer \leq 0)$
Input	careGetMinWeight?m, careGetWeight?w
Output	WeightTone!false, lowerAge!true, WeightLTmin!false
Postcondition	Timer = 1440

look \Rightarrow look tooLessWeight	
Precondition	$w < m$
Input	careGetMinWeight?m, careGetWeight?w
Output	WeightTone!true, lowerAge!false, WeightLTmin!true
Postcondition	Timer = 1440



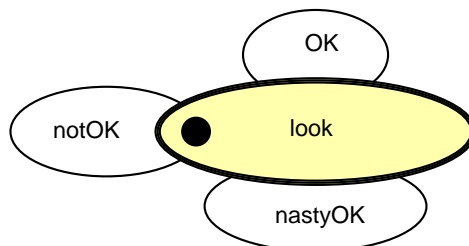
Check \Rightarrow Check MaxAge > Age ?	
Precondition	MaxAge * 1440 > Age
Input	careGetMaxAge?MaxAge, careTimer?Age
Output	careReset!true, kbdIsDead!true
Postcondition	



look \Rightarrow look OK	
Precondition	$(s \geq 3) \ \&\& \ ((k \neq 15) \ \ ((k == 15) \ \&\& \ (s \geq \text{oldValue})))$
Input	careGetSatiation?s, satGetKind?k
Output	SatiationTone!false, nastySat Tone!false, SatiationLT3!false
Postcondition	oldValue = s

look \Rightarrow look nastyOK	
Precondition	$(s \geq 3) \ \&\& \ (k == 15) \ \&\& \ (s < \text{oldValue})$
Input	careGetSatiation?s, satGetKind?k
Output	SatiationTone!false, nastySat Tone!true, SatiationLT3!false
Postcondition	oldValue = s

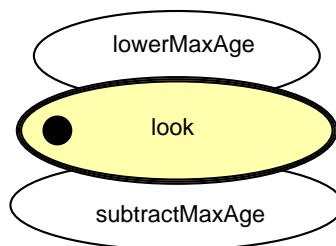
look \Rightarrow look notOK	
Precondition	$(s < 3)$
Input	careGetSatiation?s
Output	SatiationTone!true, nastySat Tone!false, SatiationLT3!true
Postcondition	oldValue = s



look \Rightarrow look OK	
Precondition	$(h \geq 3) \ \&\& \ ((k \neq 15) \ \ (h \geq \text{oldValue}))$
Input	careGetHappyness?h, hapGetKind?k
Output	HappynessTone!false, nastyHappTone!false, HappynessLT3!false
Postcondition	oldValue = h

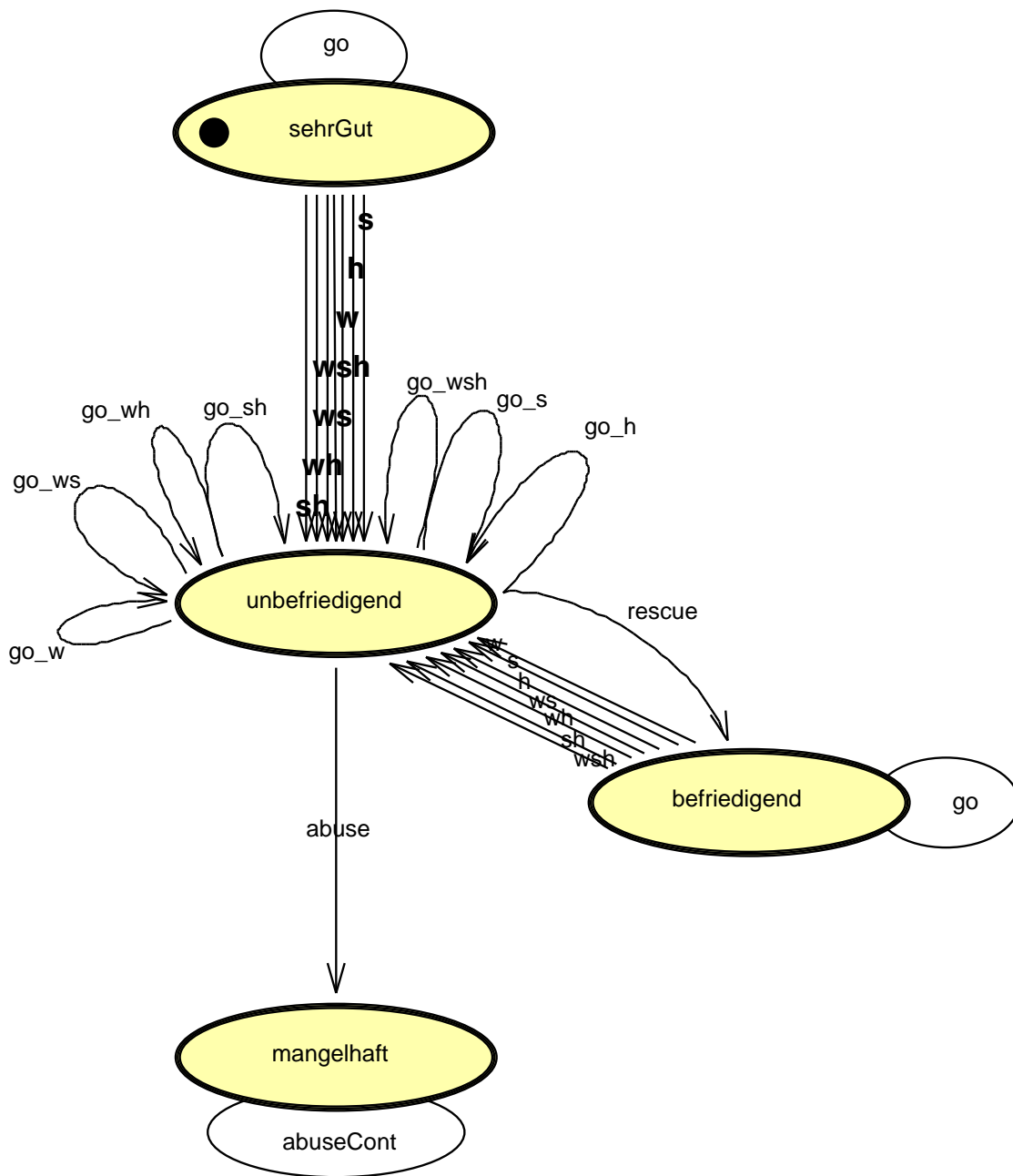
look \Rightarrow look nastyOK	
Precondition	$(h \geq 3) \ \&\& \ (k == 15) \ \&\& \ (h < \text{oldValue})$
Input	careGetHappyness?h, hapGetKind?k
Output	HappynessTone!false, nastyHappTone!true, HappynessLT3!false
Postcondition	oldValue = h

look \Rightarrow look notOK	
Precondition	$(h < 3)$
Input	careGetHappyness?h
Output	HappynessTone!true, nastyHappTone!false, HappynessLT3!true
Postcondition	oldValue = h



look \Rightarrow look lowerMaxAge	
Precondition	$((k == 11) \ \&\& \ (cs > 1)) \ \ ((k == 13) \ \&\& \ (cs > 2))$
Input	ageKind?k, ageCareState?cs, lowerAge?false
Output	memAddMaxCareAge!-1
Postcondition	

look \Rightarrow look subtractMaxAge	
Precondition	lowerAge?true
Input	
Output	memAddMaxCareAge!-1
Postcondition	



sehrGut \Rightarrow unbefriedigend	
s	
Precondition	
Input	WeightLTmin?, SatiationLT3?true, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

sehrGut \implies unbefriedigend h	
Precondition	
Input	WeightLTmin?, SatiationLT3?, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

sehrGut \implies unbefriedigend w	
Precondition	
Input	WeightLTmin?true, SatiationLT3?, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

sehrGut \implies sehrGut go	
Precondition	
Input	WeightLTmin?, SatiationLT3?, HappynessLT3?
Output	mcCareState!1, ageCareState!1
Postcondition	

unbefriedigend \implies unbefriedigend go_w	
Precondition	Timer > 0
Input	WeightLTmin?true, SatiationLT3?, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = Timer - 1

sehrGut \implies unbefriedigend wsh	
Precondition	
Input	WeightLTmin?true, SatiationLT3?true, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

sehrGut \implies unbefriedigend ws	
Precondition	
Input	WeightLTmin?true, SatiationLT3?true, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

sehrGut \implies unbefriedigend wh	
Precondition	
Input	WeightLTmin?true, SatiationLT3?, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

sehrGut \Rightarrow unbefriedigend sh	
Precondition	
Input	WeightLTmin?, SatiationLT3?true, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

unbefriedigend \Rightarrow unbefriedigend go_s	
Precondition	Timer > 0
Input	WeightLTmin?, SatiationLT3?true, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = Timer - 1

unbefriedigend \Rightarrow unbefriedigend go_h	
Precondition	Timer > 0
Input	WeightLTmin?, SatiationLT3?, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = Timer - 1

unbefriedigend \Rightarrow unbefriedigend go_ws	
Precondition	Timer > 0
Input	WeightLTmin?true, SatiationLT3?true, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = Timer - 1

unbefriedigend \Rightarrow unbefriedigend go_wh	
Precondition	Timer > 0
Input	WeightLTmin?true, SatiationLT3?, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = Timer - 1

unbefriedigend \Rightarrow unbefriedigend go_sh	
Precondition	Timer > 0
Input	WeightLTmin?, SatiationLT3?true, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = Timer - 1

unbefriedigend \Rightarrow unbefriedigend go_wsh	
Precondition	Timer > 0
Input	WeightLTmin?true, SatiationLT3?true, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = Timer - 1

unbefriedigend \implies mangelhaft abuse	
Precondition	Timer \leq 0
Input	
Output	mcCareState!3, ageCareState!3
Postcondition	

mangelhaft \implies mangelhaft abuseCont	
Precondition	
Input	
Output	mcCareState!3, ageCareState!3
Postcondition	

unbefriedigend \implies befriedigend rescue	
Precondition	
Input	WeightLTmin?, SatiationLT3?, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	

befriedigend \implies unbefriedigend w	
Precondition	
Input	WeightLTmin?true, SatiationLT3?, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

befriedigend \implies unbefriedigend s	
Precondition	
Input	WeightLTmin?, SatiationLT3?true, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

befriedigend \implies unbefriedigend h	
Precondition	
Input	WeightLTmin?, SatiationLT3?, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

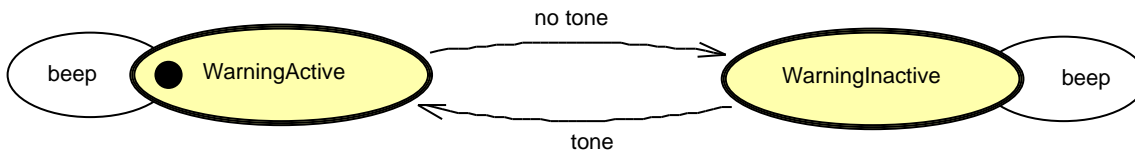
befriedigend \implies unbefriedigend ws	
Precondition	
Input	WeightLTmin?true, SatiationLT3?true, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

befriedigend \Rightarrow unbefriedigend wh	
Precondition	
Input	WeightLTmin?true, SatiationLT3?, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

befriedigend \Rightarrow unbefriedigend sh	
Precondition	
Input	WeightLTmin?, SatiationLT3?true, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

befriedigend \Rightarrow unbefriedigend wsh	
Precondition	
Input	WeightLTmin?true, SatiationLT3?true, HappynessLT3?true
Output	mcCareState!2, ageCareState!2
Postcondition	Timer = 120

befriedigend \Rightarrow befriedigend go	
Precondition	
Input	WeightLTmin?, SatiationLT3?, HappynessLT3?
Output	mcCareState!2, ageCareState!2
Postcondition	



WarningActive \Rightarrow WarningInactive no tone	
Precondition	
Input	careWarningActive?false, SatiationTone?false, nastySat-Tone?false, WeightTone?false, HappynessTone?false, nasty-HappTone?false
Output	
Postcondition	

WarningInactive \implies WarningActive tone	
Precondition	
Input	careWarningActive?true, WeightTone?false, SatiationTone?false, nastySatTone?false, HappynessTone?false, nastyHappTone?false
Output	
Postcondition	

WarningActive \implies WarningActive beep	
Precondition	
Input	x1 x2 x3 x4 x5 WeightTone?x1, SatiationTone?x2, nastySatTone?x3, HappynessTone?x4, nastyHappTone?x5
Output	dspBeep!true
Postcondition	

WarningInactive \implies WarningInactive beep	
Precondition	
Input	x1 x2 nastySatTone?x1, nastyHappTone?x2
Output	dspBeep!true
Postcondition	